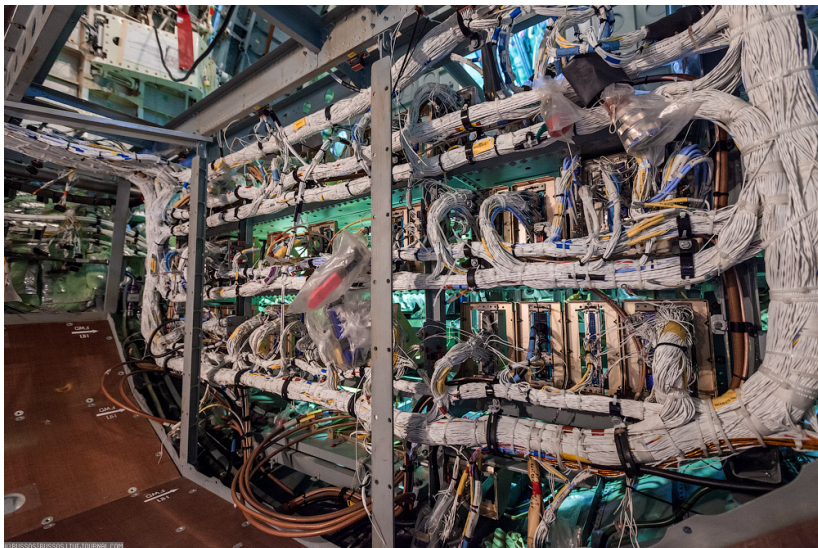


# Performance Enhancement of Extended AFDX via Bandwidth Reservation for TSN/BLS Shapers

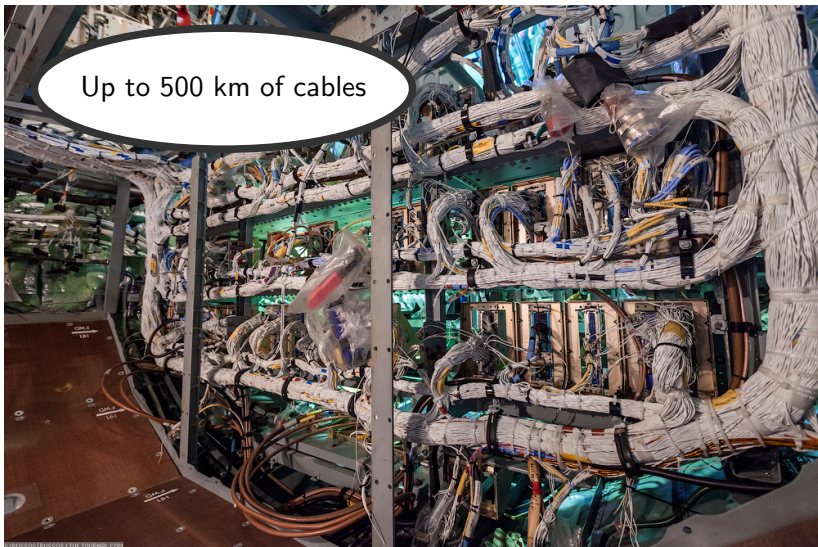
Anaïs Finzi, Ahlem Mifdaoui et al.

July 3, 2018, RTN'18

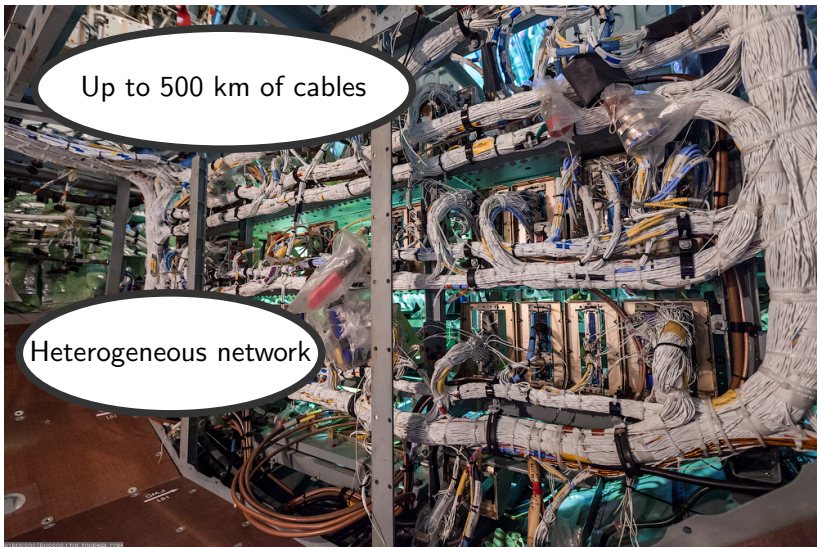
# Context and Objectives



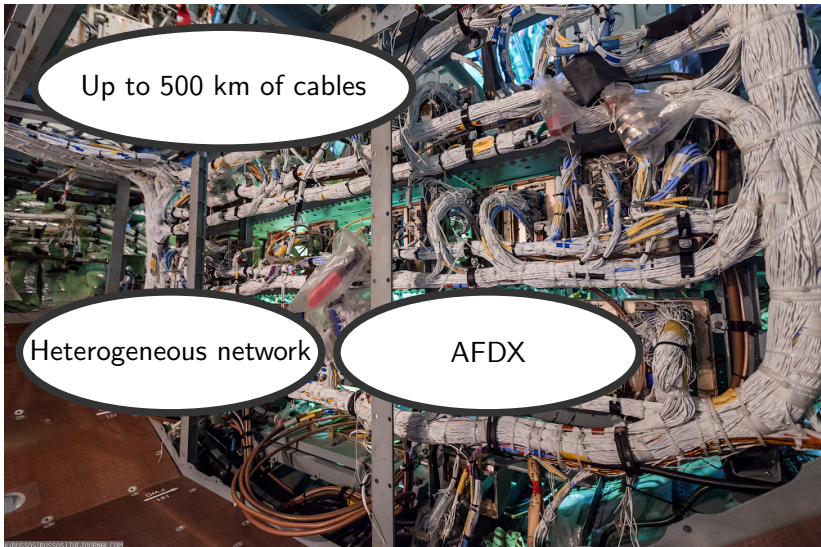
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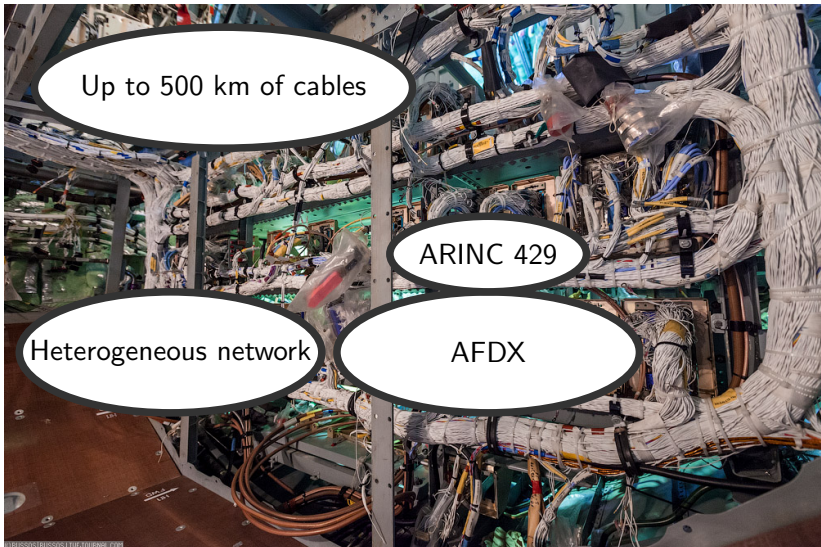
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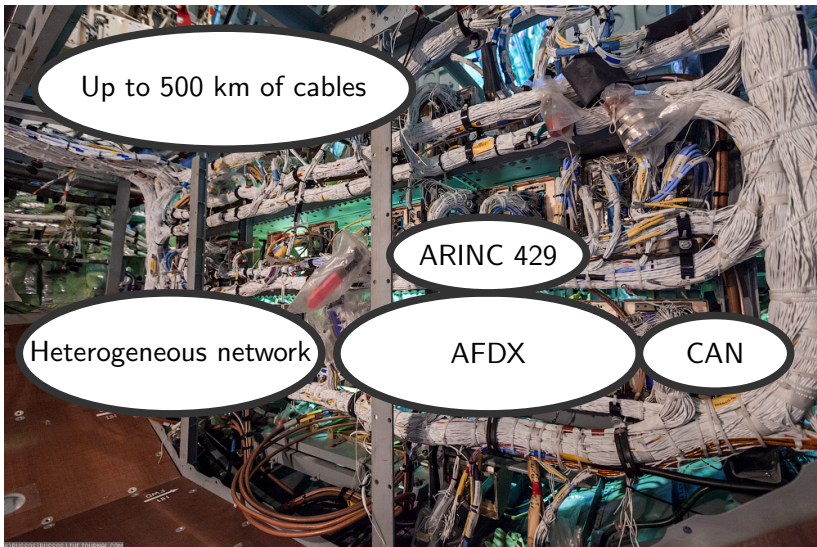
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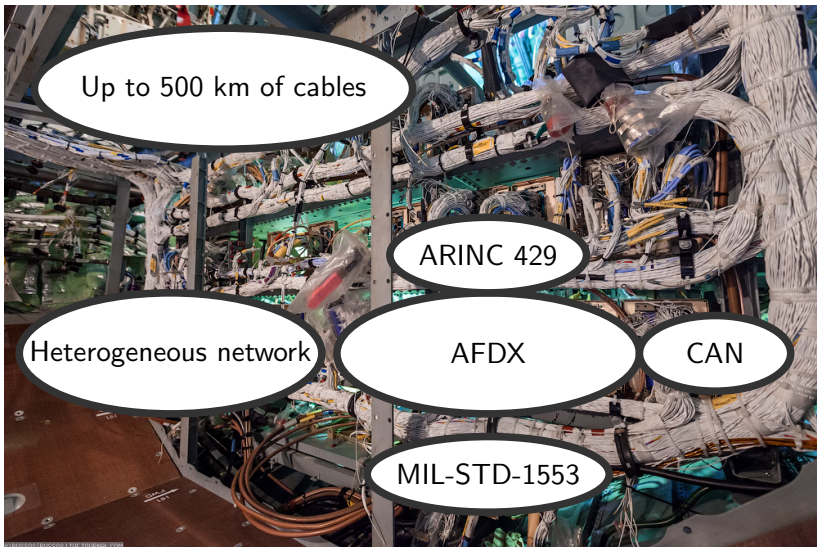
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# Context and Objectives

## Current Avionics Communication Architecture limitations

- **Heterogeneity**: high complexity, delays and costs
- **One criticality level**: backbone supports only essential traffic
- **Unfair service policy**: strong impact of high priorities

# Context and Objectives

## Current Avionics Communication Architecture limitations

- **Heterogeneity**: high complexity, delays and costs
- **One criticality level**: backbone supports only essential traffic
- **Unfair service policy**: strong impact of high priorities

## Main Objective

**Homogenize avionics communication architecture**

→ *Extend the backbone network to support **Safety-Critical** and **Best-Effort** Traffics*

# Avionics Requirements and Challenges

## Requirements

- **Predictability** : guaranteeing schedulability constraints, i.e. bounded delays respecting deadlines
- **Modularity** : minimizing the (re)configuration effort

# Avionics Requirements and Challenges

## Requirements

- **Predictability** : guaranteeing schedulability constraints, i.e. bounded delays respecting deadlines
- **Modularity** : minimizing the (re)configuration effort

## Challenges

- ↘ **Complexity** : Reduce the implementation and configuration effort
- ↗ **Fairness** : Limit the impact of high priorities on lower ones

# Promising Solution

Solutions	TTE <sup>1</sup>	TAS <sup>2</sup>	PS <sup>3</sup>	UBS <sup>4</sup>	BLS <sup>5</sup>	CBS <sup>6</sup>	NP-SP <sup>7</sup>	DRR <sup>8</sup>
Modularity	X	X	X	✓✓	✓✓	✓✓	✓✓	✓✓
Predictability	✓✓	✓✓	✓✓	✓✓	✓✓	✓	✓✓	✓✓
Fairness	X	X	✓	✓✓	✓✓	✓✓	X	✓✓
Complexity	X	X	X	X	✓✓	✓✓	✓✓	✓

Existing solutions vs avionics requirements and challenges

✓✓: 😊

✓: 😐

X: 😞

---

<sup>1</sup>Time Triggered Ethernet

<sup>2</sup>Time Aware Shaper

<sup>3</sup>Peristaltic Shaper

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# Promising Solution

## Schedulers

Solutions	TTE <sup>1</sup>	TAS <sup>2</sup>	PS <sup>3</sup>	UBS <sup>4</sup>	BLS <sup>5</sup>	CBS <sup>6</sup>	NP-SP <sup>7</sup>	DRR <sup>8</sup>
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# Promising Solution

## TTTEch

## Schedulers

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# Promising Solution

TTTEch

IEEE Time Sensitive Networking

Schedulers

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Existing solutions vs avionics requirements and challenges



→ **the Burst Limiting Shaper is the most promising solution**

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# Followed Methodology

## Specification of an Extended AFDX

→ **Low complexity** and few hardware/software modifications<sup>a</sup>

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## Formal timing analysis

→ New Network Calculus model with **good tightness**<sup>a</sup>

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## Performance Enhancement

→ **Bandwidth Reservation** methods for TSN/BLS to enhance system **schedulability**

# Outline

- 1 System Model
- 2 Bandwidth Reservation Methods
- 3 Performance Evaluation
- 4 Conclusion and perspectives

# Outline

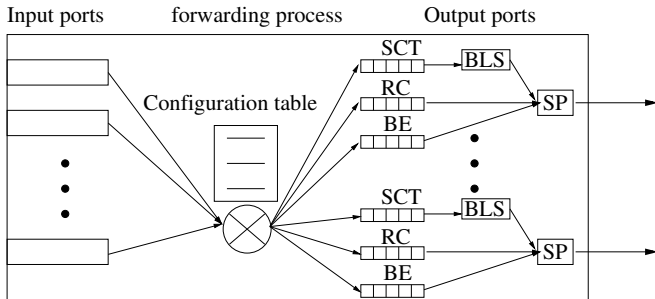
- 1 System Model
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# Extended AFDX Switch

## 1-Gigabit AFDX Switch architecture

We consider 3 types of traffics: Safety Critical Traffic (SCT), Rate Constrained (RC), and Best-Effort (BE).

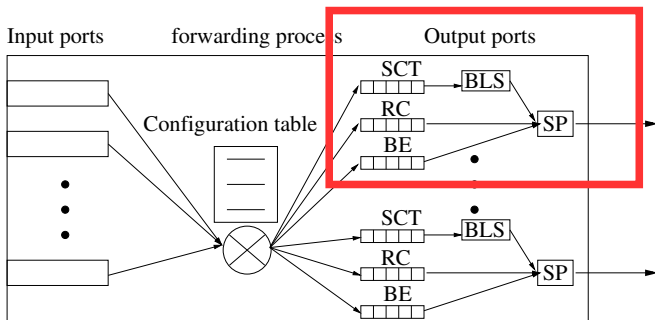


Proposed switch architecture

# Extended AFDX Switch

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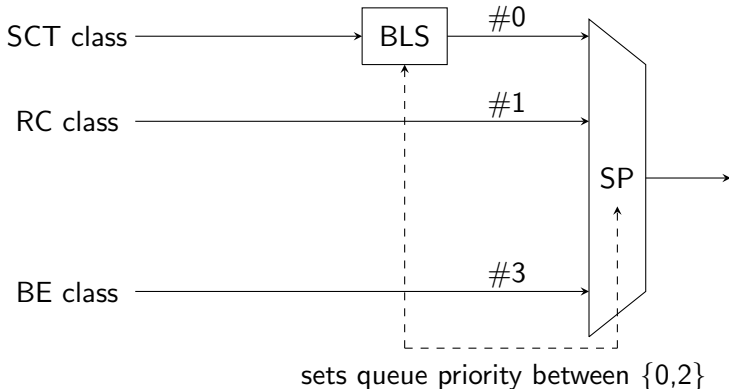
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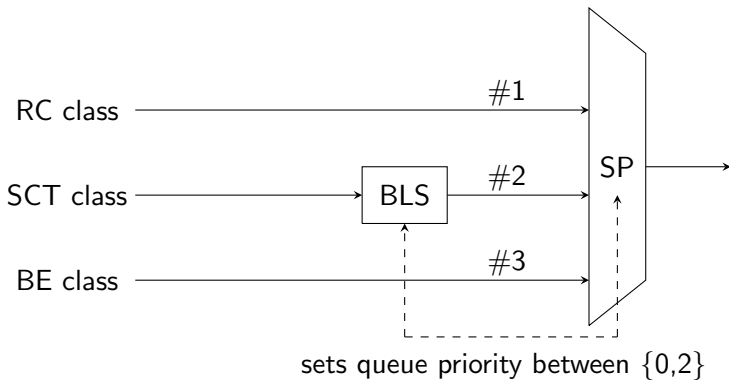
# Extended AFDX output port

3-classes example: high BLS priority



# Extended AFDX output port

3-classes example: low BLS priority



# Burst Limiting Shaper Parameters

Each BLS credit has 3 parameters:

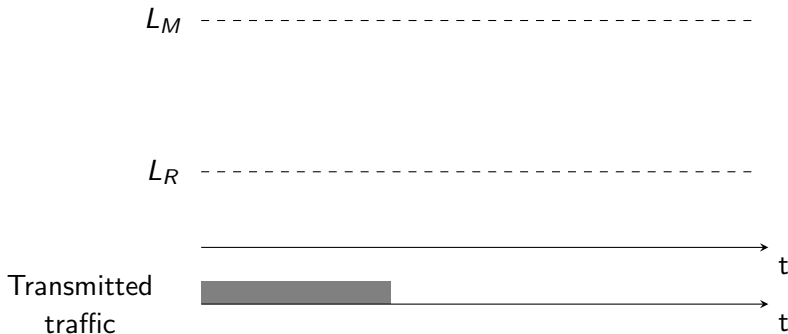
- Maximum Level ( $L_M$ )
- Resume Level ( $L_R$ )
- Reserved Bandwidth (BW)

BW is used with the output link capacity  $C$  to compute the credit slopes as follows:

- the sending slope,  $I_{send} = (1 - BW) \cdot C$
- the idle slope,  $I_{idle} = BW \cdot C$

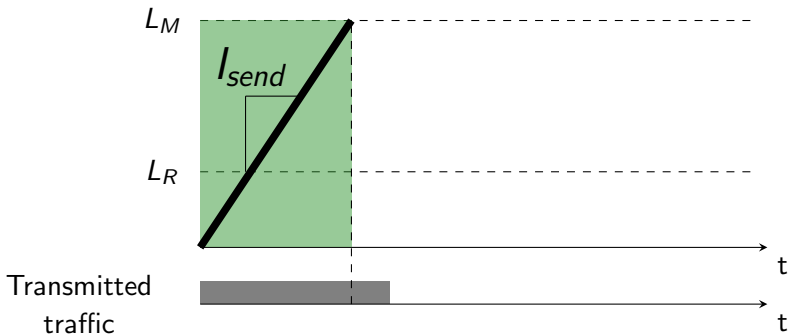
# Burst Limiting Shaper credit evolution

Bursty traffic



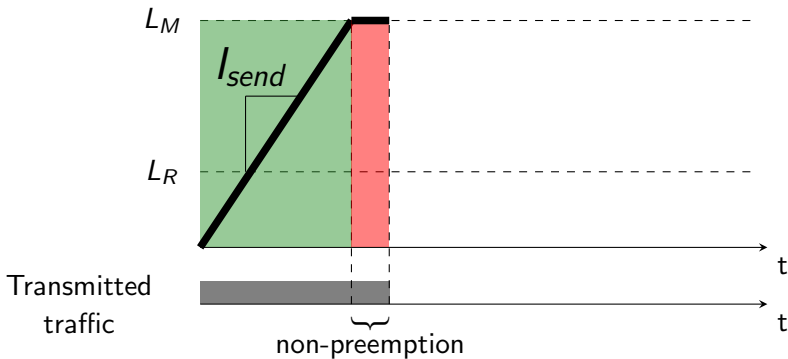
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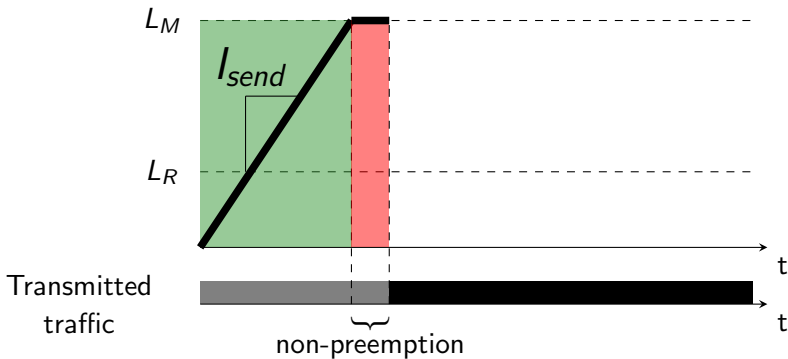
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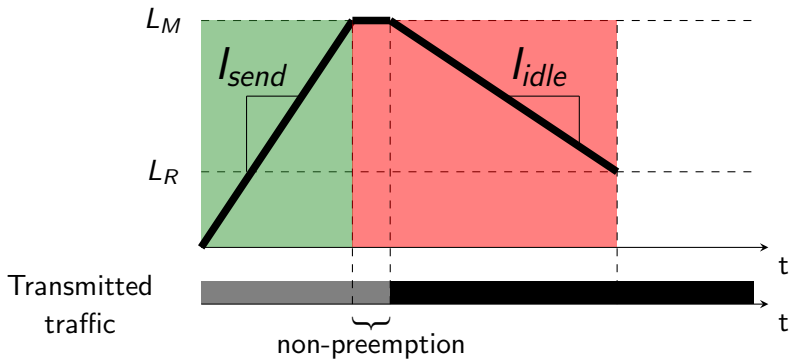
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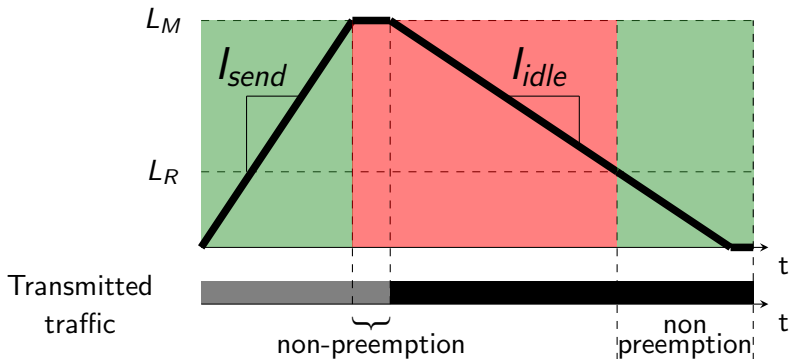
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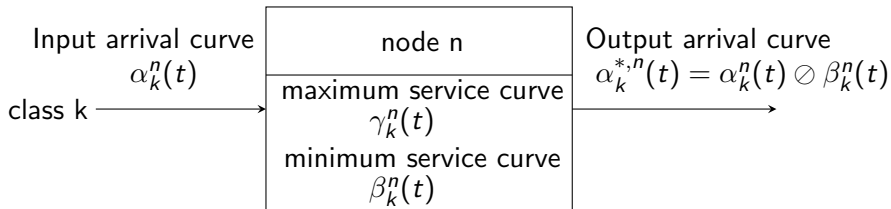
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# Network calculus

Characteristics of an aggregate traffic of class  $k$  crossing the node  $n$

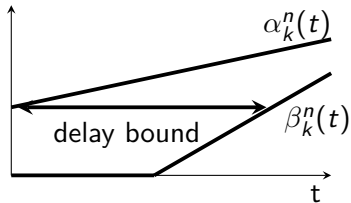
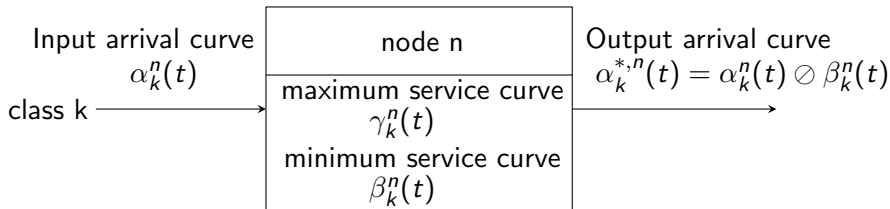


$$f \circledast g(t) = \sup_{s \geq 0} \{f(t+s) - g(s)\}$$

$$f \circledast g(t) = \inf_{0 \leq s \leq t} \{f(t-s) + g(s)\}$$

# Network calculus

Characteristics of an aggregate traffic of class  $k$  crossing the node  $n$

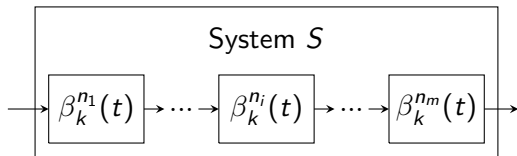
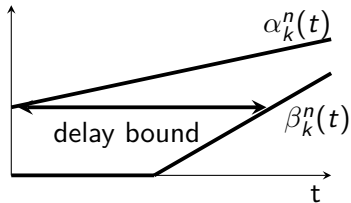
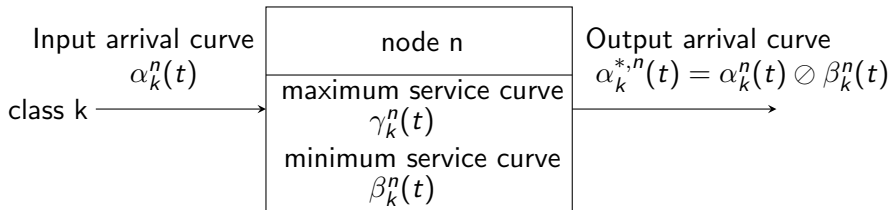


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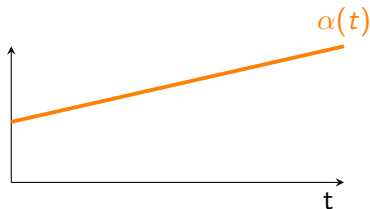
$$\beta_k^S(t) = \beta_k^{n_1}(t) \otimes \dots \otimes \beta_k^{n_i}(t) \otimes \dots \otimes \beta_k^{n_m}(t)$$

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# Traffic and Network Model

Traffic modelisation: **leaky buckets**



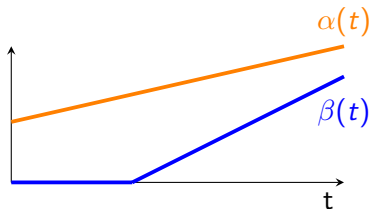
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Node modelisation: **rate-latency**



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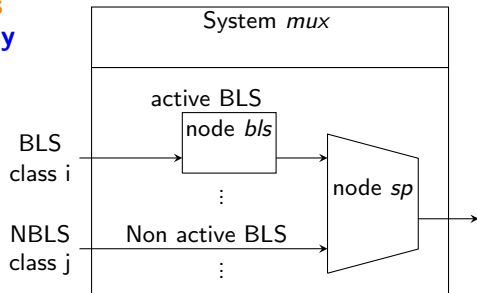
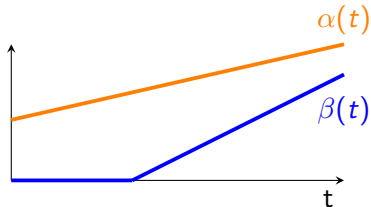
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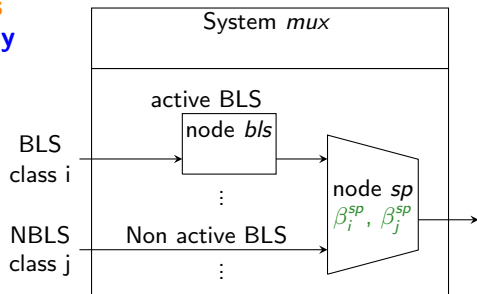
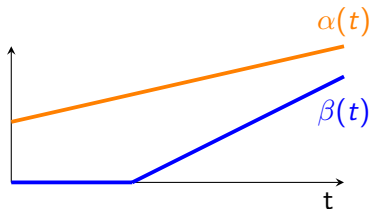
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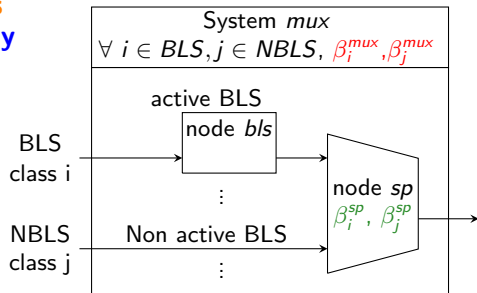
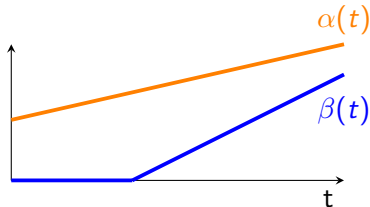
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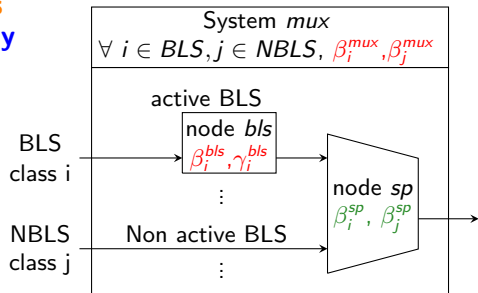
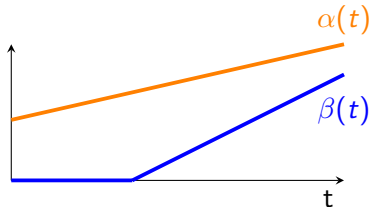
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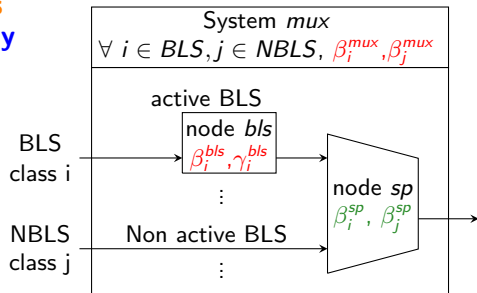
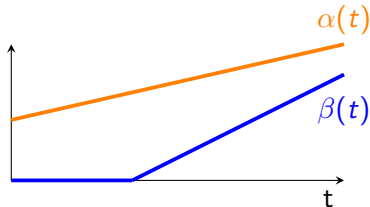
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## Objective

Find the reserved BLS bandwidth **minimizing RC delay bounds** for each **flow** along its **path**

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Find the reserved BLS bandwidth **minimizing RC delay bounds** for each **flow** along its **path**

## Constraints

- **Class rate constraint:** in each output port, the class rate is lower than the guaranteed service rate
- **Aggregate rate constraint:** the total load of an output port is lower than the total capacity  $C$
- **Deadline constraints:** the delay bound of each traffic class is lower than its deadline



# Problem Formulation

$$\forall f \in RC, \forall mux \in path_f,$$

$$\underset{L_M^{mux}, L_R^{mux}, BW^{mux}}{\text{minimize}} \quad EED_{RC,f}(L_M^{mux}, L_R^{mux}, BW^{mux})$$

$$\text{s.t. } \forall f \text{ in } j \in \{SCT, RC\}, \forall mux \in path_f :$$

$$R_j^{mux} \geq \sum_{f \in F_j^{mux}} r_f$$

$$\sum_{g \in F_{SCT}^{mux}} r_g + \sum_{f \in F_{RC}^{mux}} r_f \leq C$$

$$Dl_f \geq EED_{j,f}(L_M^{mux}, L_R^{mux}, BW^{mux})$$

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A complexity of  $O(l^m \cdot N^{3 \cdot m})$  for  $m$  ports and  $l$  flows.

# Problem Solving

## Relaxed Objective

Find the reserved BLS bandwidth **minimizing RC delay bounds** for each **class** within each **output** port

→ Reducing the complexity down to  $O(m \cdot N^3)$

→ Need to define a **local Deadline** within each output port

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## Solving the problem based on Heuristics

- The optimisation problem is a **non-linear** problem
- Take advantage of conducted **sensitivity analysis** of the analytical model to deduce **heuristics**

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## Solving the problem based on Heuristics

- The optimisation problem is a **non-linear** problem
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## Two proposed methods to compute the local deadlines

- **Heuristic Deadline**: defined proportionally to the port load
- **Dichotomous Deadline**: defined accurately in each port

# Outline

- 1 System Model
- 2 Bandwidth Reservation Methods
- 3 Performance Evaluation**
- 4 Conclusion and perspectives

# 1-Gigabit Avionics Case study

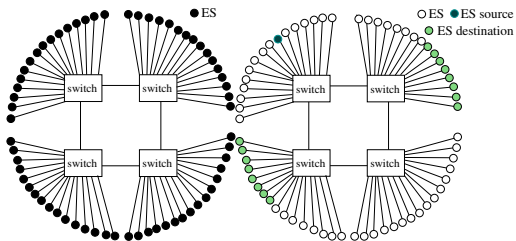


Figure: Multi-hop network and traffic communication pattern

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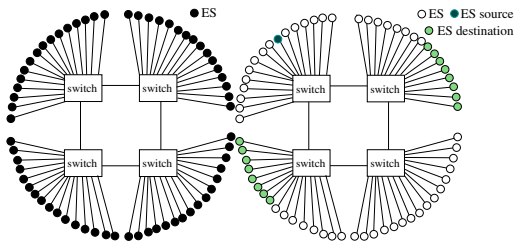


Figure: Multi-hop network and traffic communication pattern

Priority	Traffic type	MFS (Bytes)	BAG (ms)	deadline (ms)	jitter (ms)
0/2	SCT	64	2	2	0
1	RC	320	2	2	0
3	BE	1024	8	none	0.5



# Numerical results

Intuitive parameters:  $BW = UR_{SCT}^{bn}$ ,  $L_R = MFS_{RC} \cdot BW$  and  
 $L_M = 80 \cdot (1 - BW) \cdot MFS_{SCT}$

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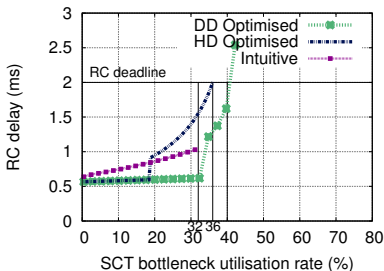
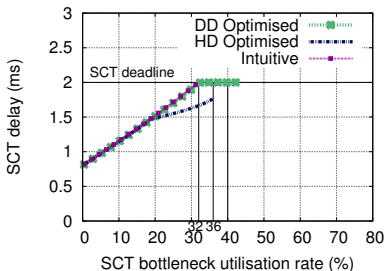
$$L_M = 80 \cdot (1 - BW) \cdot MFS_{SCT}$$

$$\text{Scenario}_{SCT} = (UR_{SCT}^{bn} \in [0.4 : 80], UR_{RC}^{bn} = 20)$$

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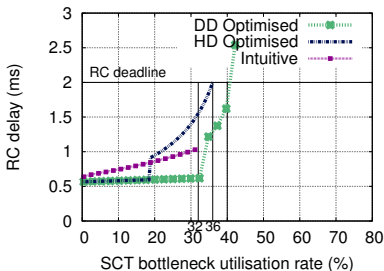
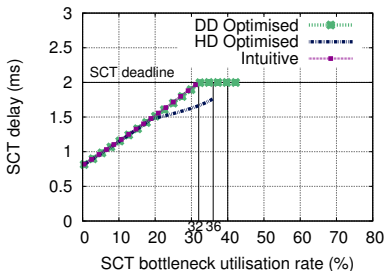
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→ **SCT schedulability is increased by up to 31% under Dichotomous Deadline method**

$UR_k^{bn}$ : bottleneck utilisation rate of class k

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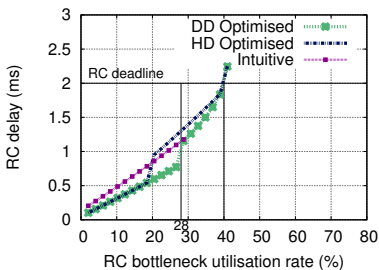
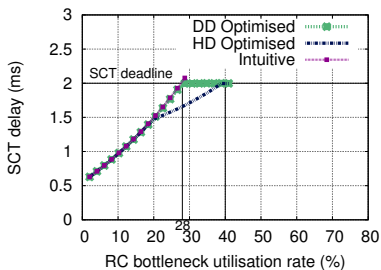
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$Scenario_{RC} = (UR_{SCT}^{bn} = 20, UR_{RC}^{bn} \in [0.4 : 80])$

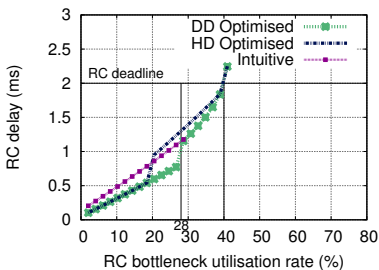
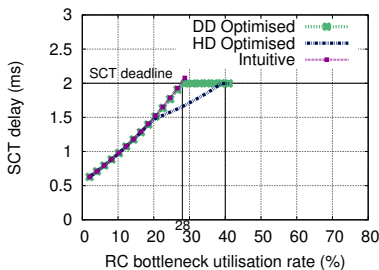
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 $Scenario_{RC} = (UR_{SCT}^{bn} = 20, UR_{RC}^{bn} \in [0.4 : 80])$



→ RC delay bounds decreased by up to 50% under  
Dichotomous Deadline method



# Numerical Results

		improvement compared to SP(%)				computation times	
		maximum RC delay at		maximum		(s) of Scenario	
		$UR_{SCT}^{bn} = 33\%$	$UR_{RC}^{bn} = 28\%$	$UR_{SCT}^{bn}$	$UR_{RC}^{bn}$	SCT	RC
HD	BLS	18	22	33	21	<b>57</b>	<b>9</b>
DD	BLS	<b>77</b>	<b>55</b>	<b>52</b>	<b>24</b>	117	233

# Numerical Results

		improvement compared to SP(%)				computation times	
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→ **Higher Complexity for Dichotomous Deadline method**

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- 4 Conclusion and perspectives**

# Conclusion and perspectives

## Two optimized bandwidth reservation methods for TSN/BLS

- **Heuristic Deadline**: simple but average performances
- **Dichotomous Deadline**: complex but good performances

## Conducted Performance evaluation on a realistic avionics case study

- Enhanced SCT **schedulability** (up to 31%) under DD
- Enhanced RC **delay** bounds (up to to 50%) under DD

# Conclusion and perspectives

## Two optimized bandwidth reservation methods for TSN/BLS

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## Conducted Performance evaluation on a realistic avionics case study

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- Enhanced RC **delay** bounds (up to to 50%) under DD

## Approach Generalization to multiple TSN/BLS classes

- Offer higher configuration flexibility

# Q&A

**Thank you for your attention**