

Techniques Optimizing the Number of Processors to Schedule Multi-Threaded Tasks

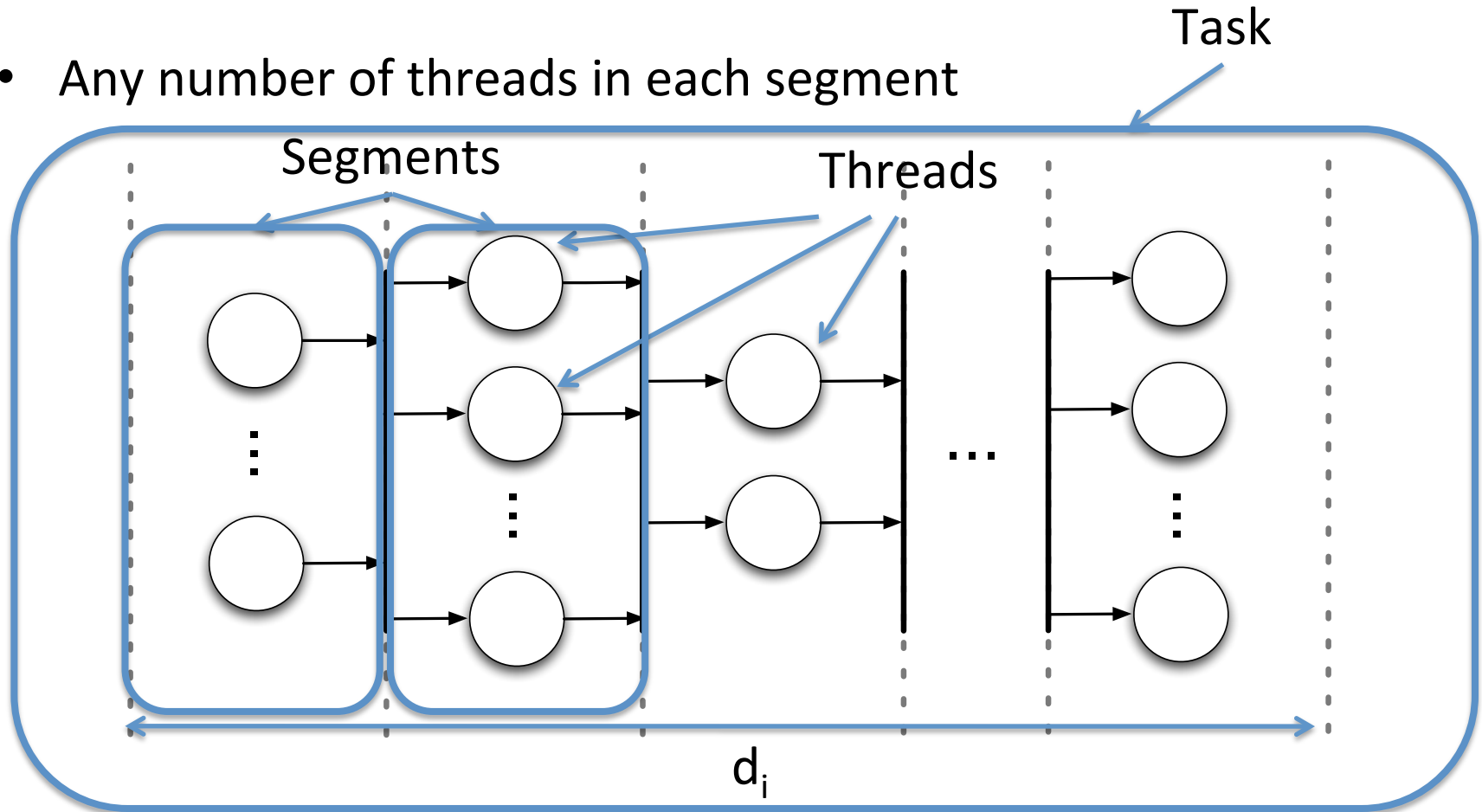
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Multiprocessor platforms purpose: Parallelization

- What can we parallelize?
 - Traditional approach: execution of many **sequential** tasks
 - But... #CPU is increasing -> Systems with more CPUs than tasks
 - New approach: execution of **parallel tasks**
 - Solid background for parallelization in the “non-real time” world
 - Explicit parallel coding : MPI, PVM, OpenMP, multi-thread
 - Compiler (automatic) parallelization
- Should we develop two different scheduling models?
- If not: How could we efficiently use the existing theory?

Generalization of the Fork-Join model

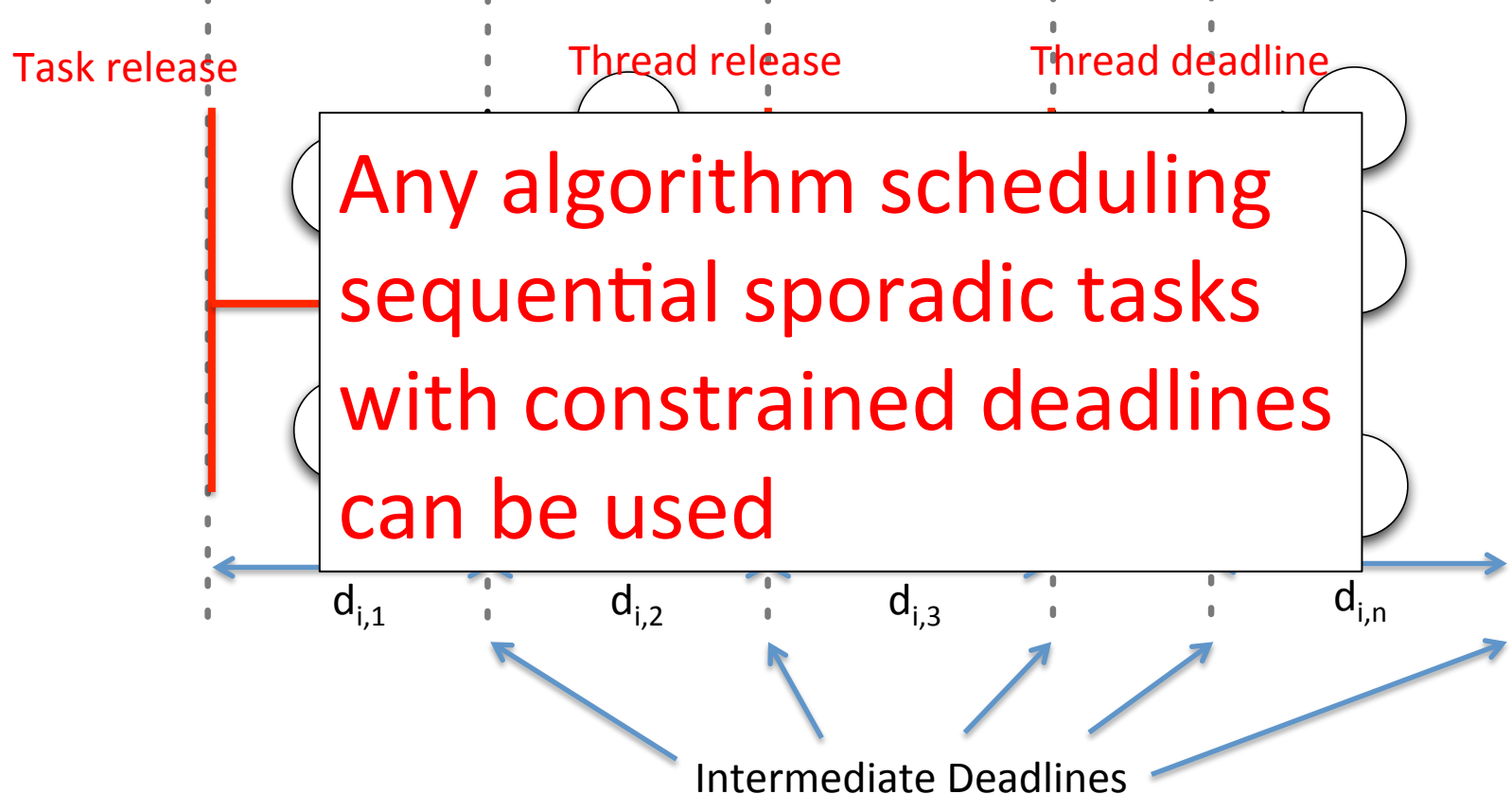
- Any number of threads in each segment



- Sporadic** multi-threaded tasks with **constrained deadlines**

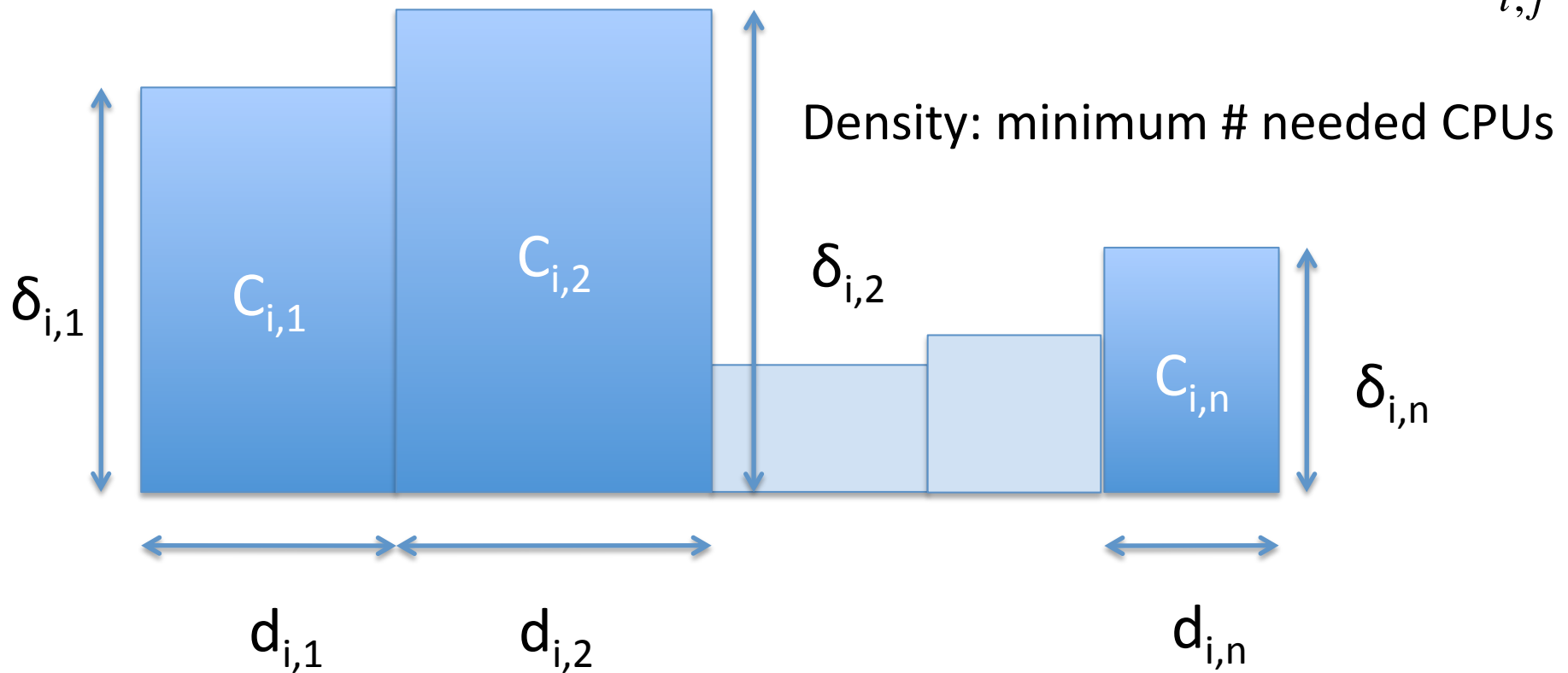
How could we use the existing scheduling theory with such a model?

- Adding artificial intermediate deadlines
- ➔ Each **thread** can be modeled by a **sequential sporadic task**

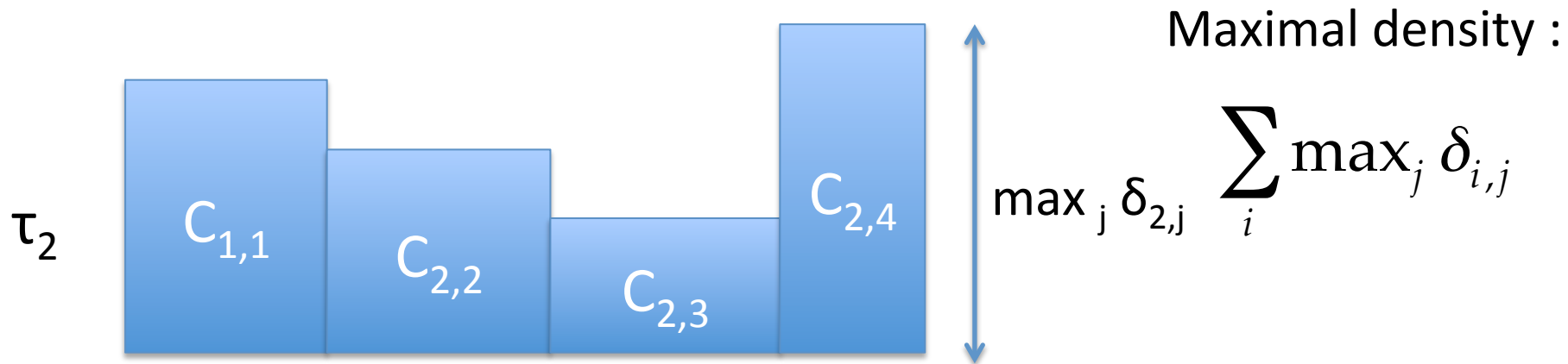
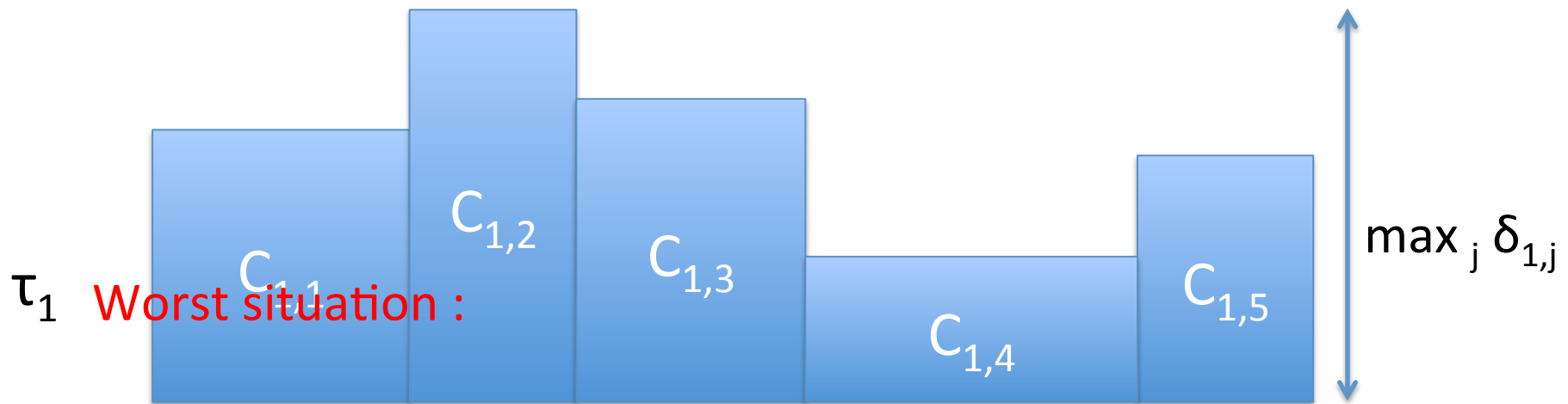


Density of a segment

Density of a segment $\tau_{i,j} : \delta_{i,j} = \frac{C_{i,j}}{d_{i,j}}$



Density of a task system



How do we minimize the number of processors?

- A sufficient schedulability test for PD², DP-Wrap, **U-EDF**:

$$m \geq \delta(t), \forall t$$

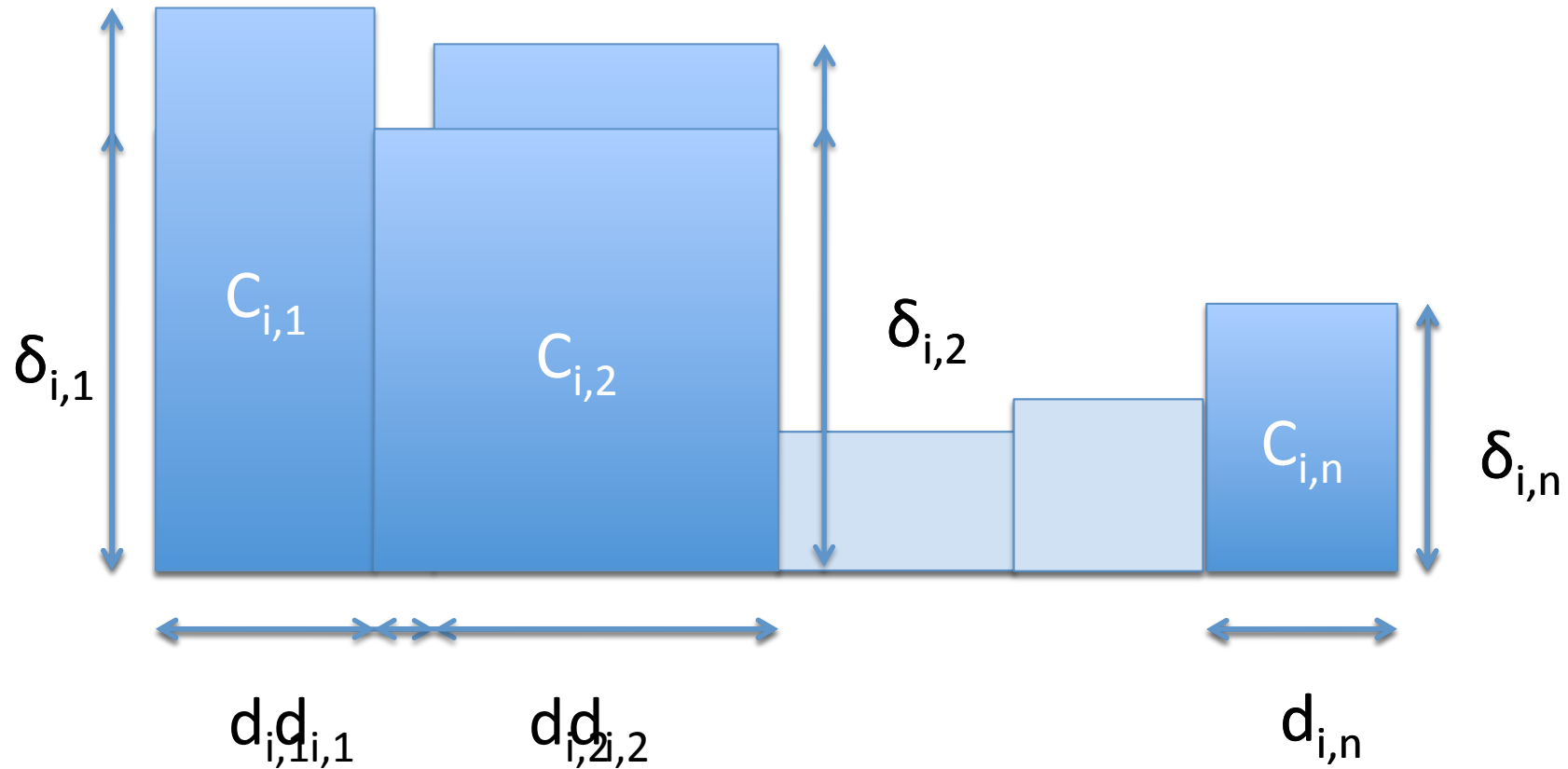
- Minimizing $m \rightarrow$ minimizing the total maximal density

$$\sum_i \max_j \delta_{i,j} = \sum_i \max_j \frac{C_{i,j}}{d_{i,j}}$$

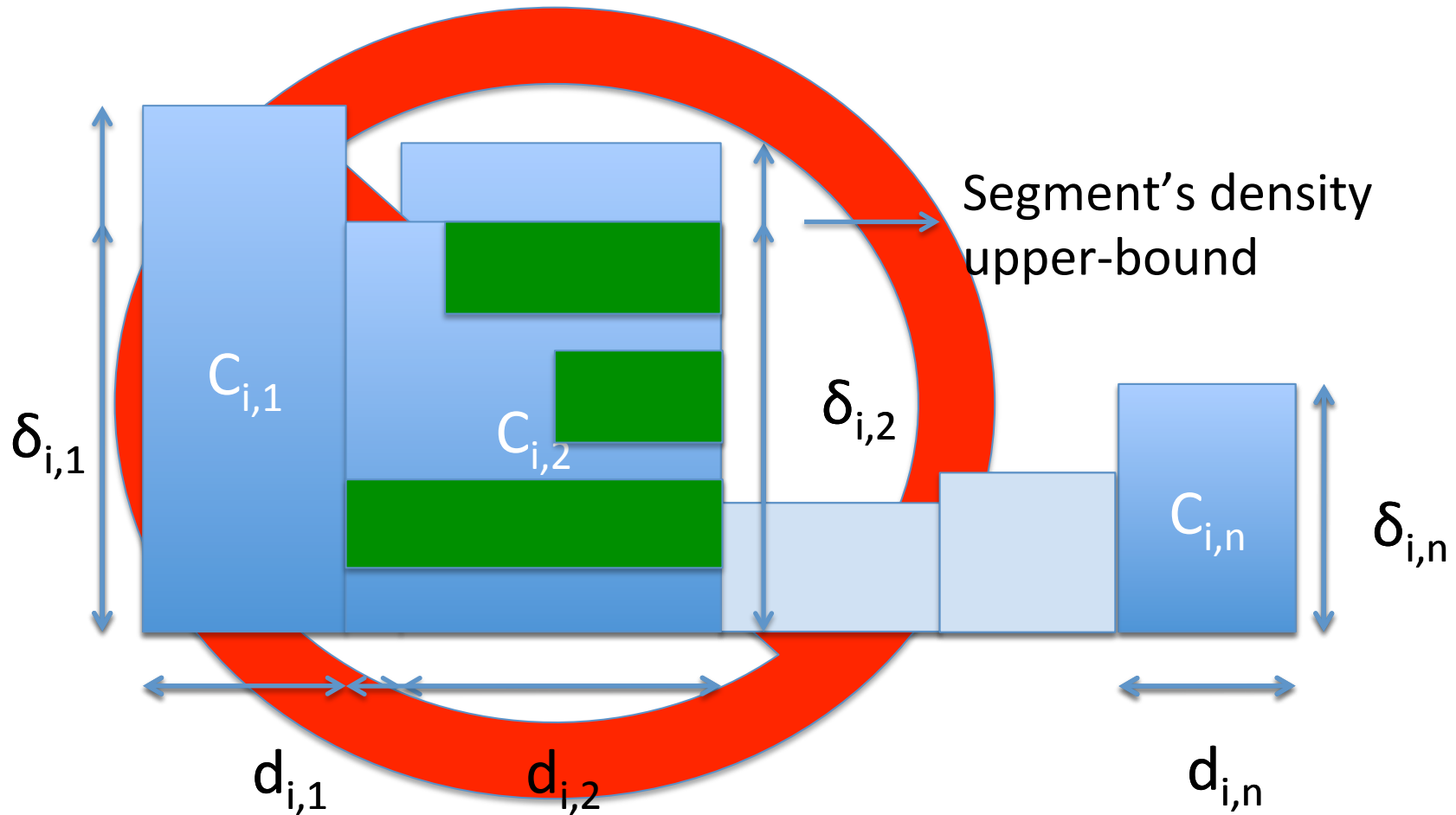
- Terms are independent \rightarrow minimizing the maximal density for each task

$$\max_j \frac{C_{i,j}}{d_{i,j}}$$

Density of a segment

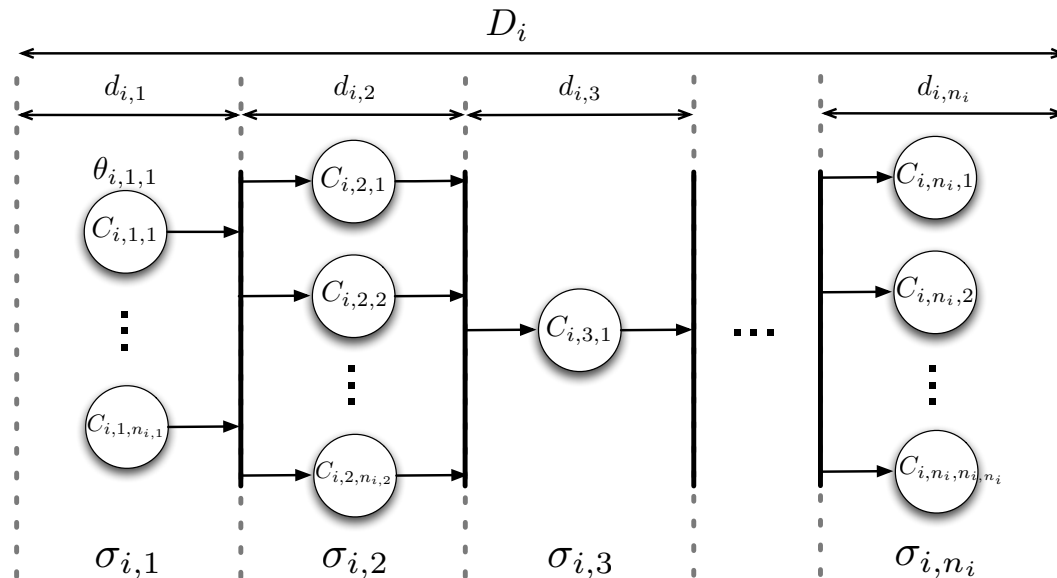


Density of a segment



This Problem can be expressed as a Linear Optimization Problem

- **Minimize:** Maximum density reachable by the segments
- **Subject to:**
 - Intermediate deadline \geq Largest thread execution (for each segment)
 - Sum of intermediate deadlines \leq Task deadline

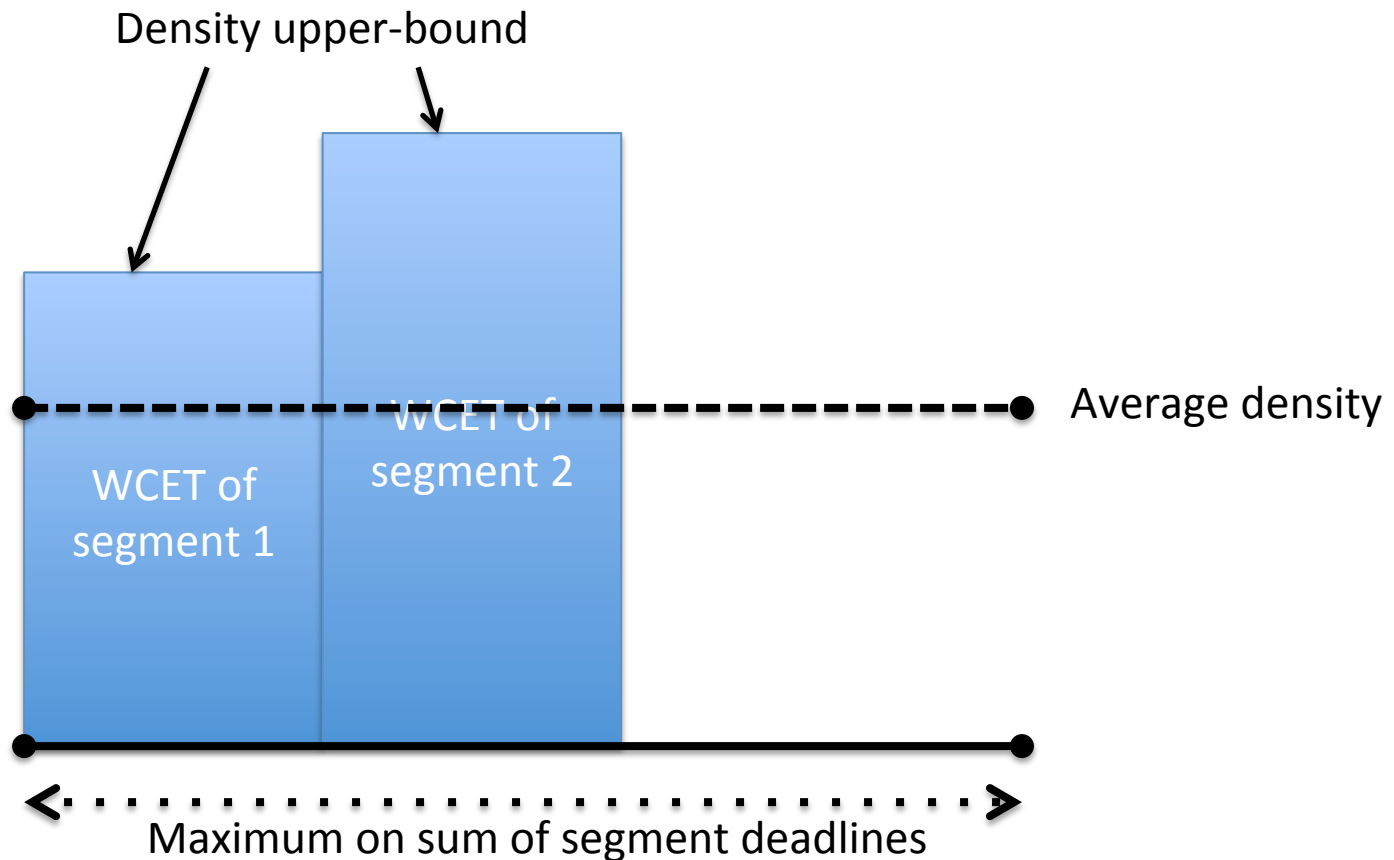


Let us try to understand the optimal solution

- The deadline of a segment cannot be smaller than the WCET of its threads
 - ➔ The segment density is upper-bounded
- An **optimal** solution can be found by **comparing** the **upper-bound of all segment densities** with the **average density** of the task

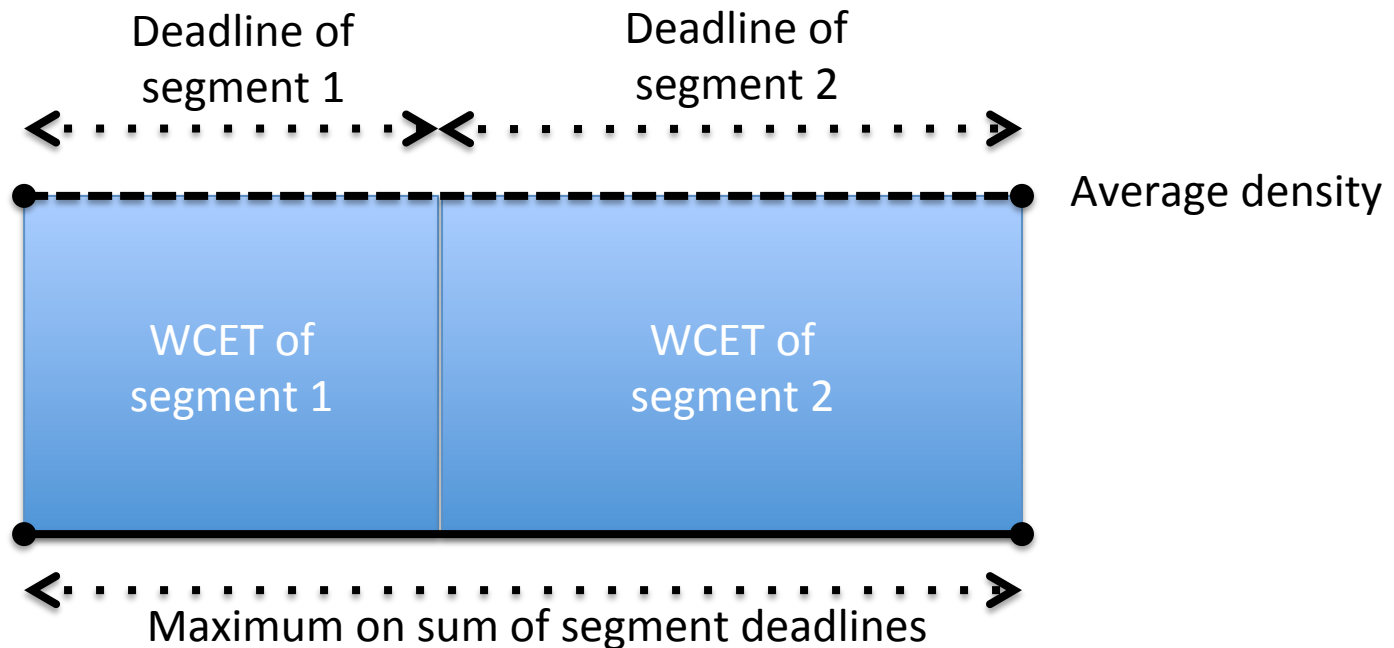
Let us try to understand the optimal solution

- **Rule 1:** Keep the density constant if possible



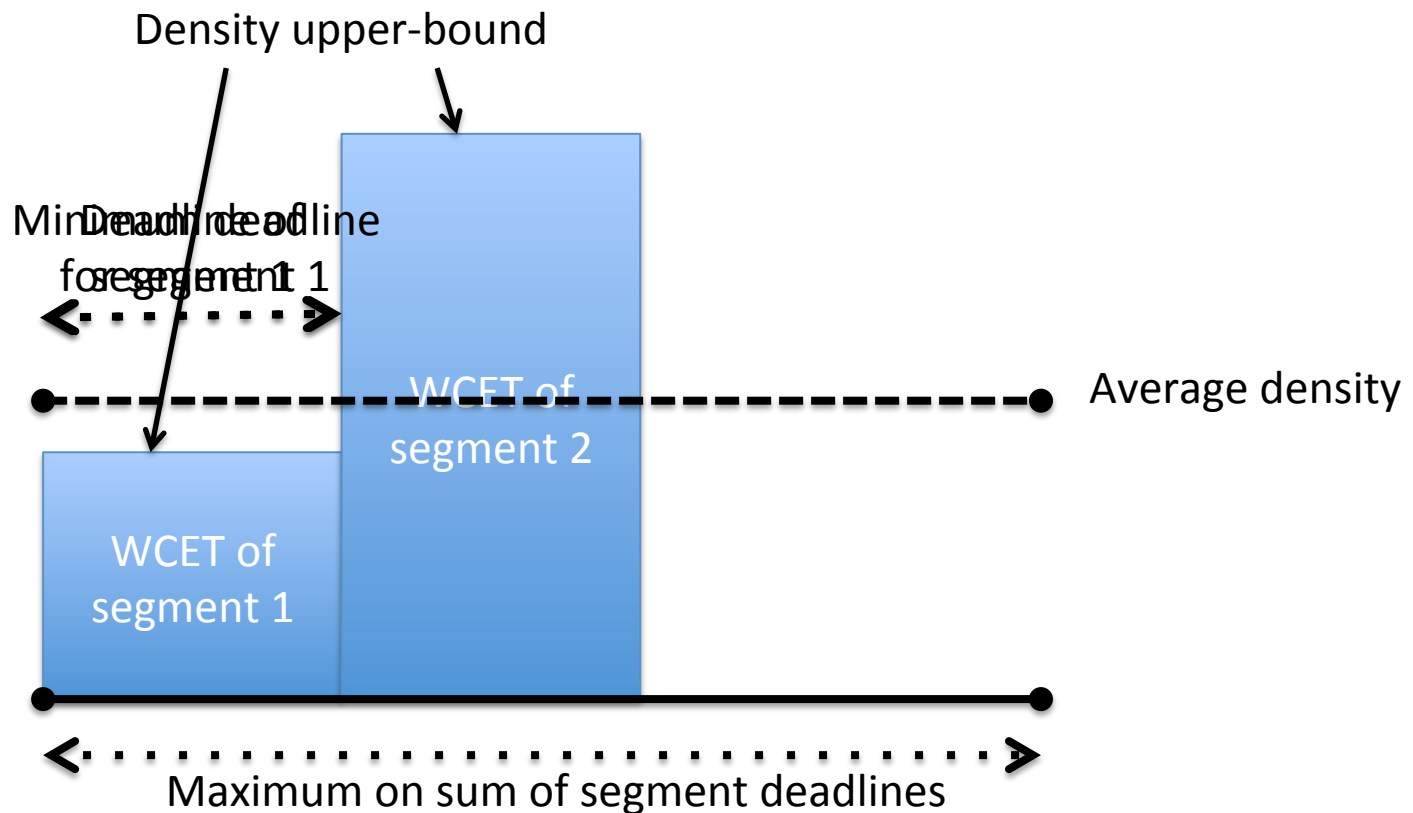
Let us try to understand the optimal solution

- **Rule 1:** Keep the density constant if possible



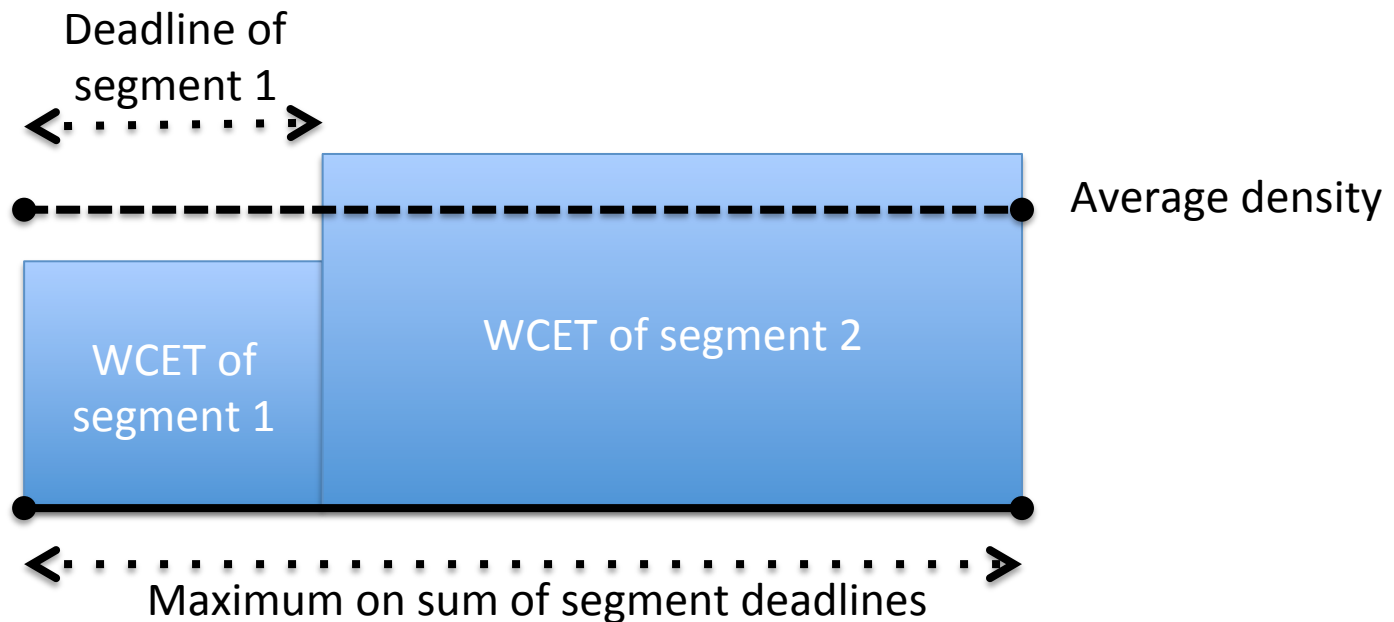
Let us try to understand the optimal solution

- **Rule 2:** Minimize impact of segments with small densities



Let us try to understand the optimal solution

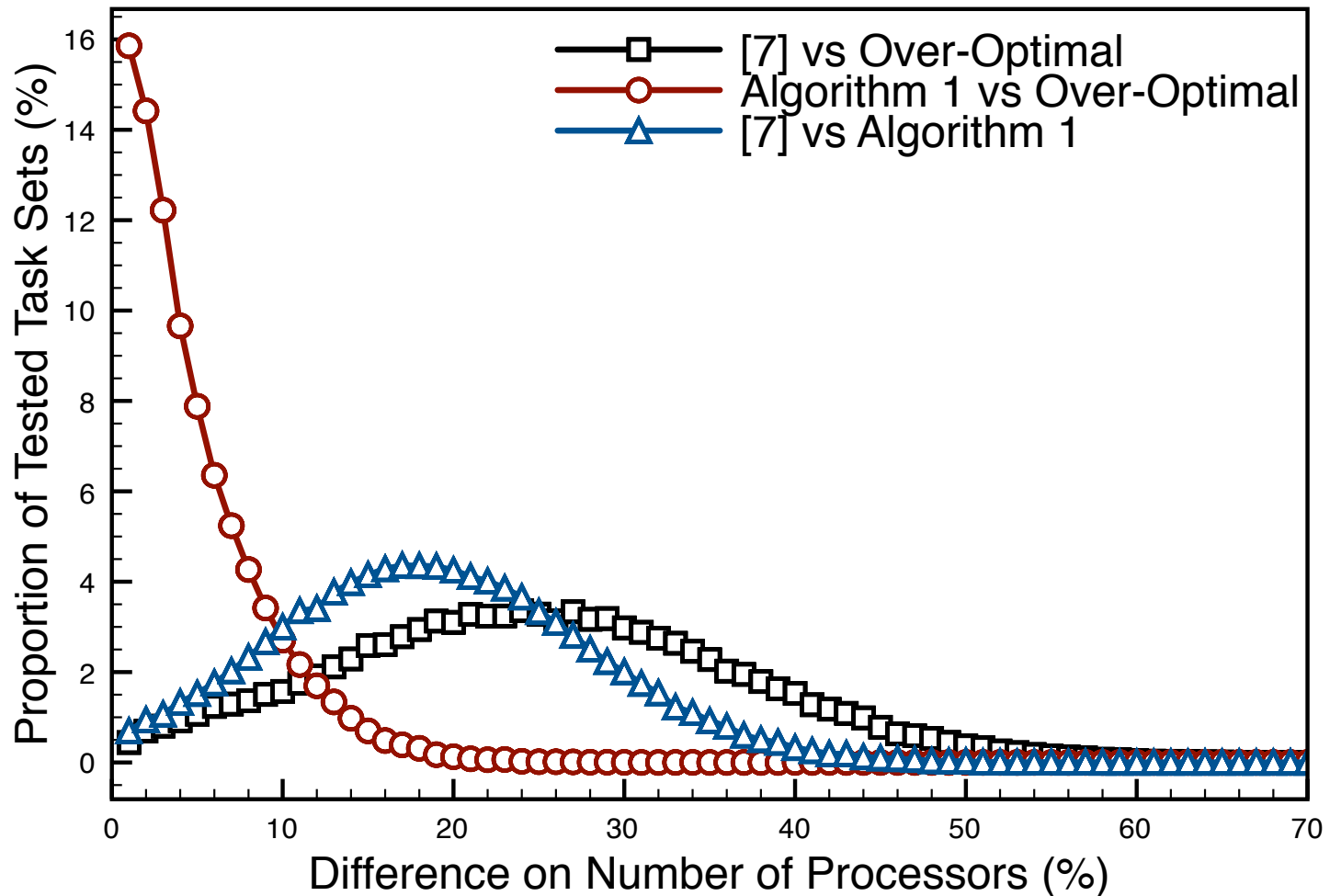
- **Rule 2:** Minimize impact of segments with small densities



A simple algorithm to find an optimal solution

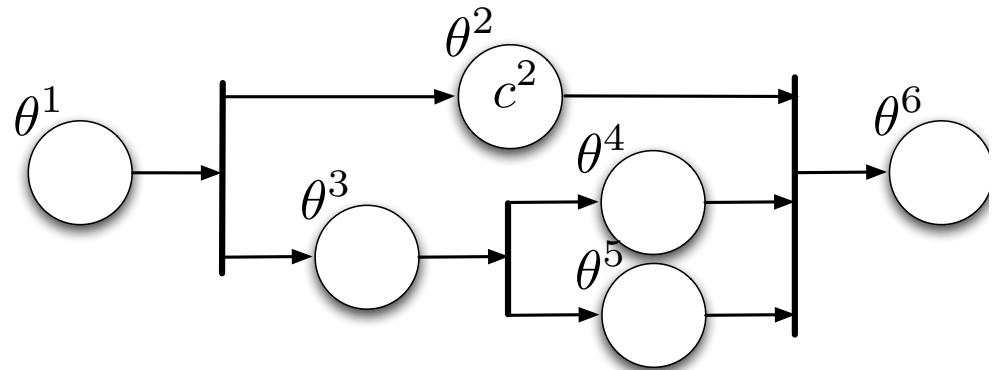
- Sort segments by their density upper-bounds
- **For each** segment in the list **DO**
 - **IF** Maximum density < average density **THEN**
 - Assign maximal density to the segment
 - Recompute average density of remaining segments
 - **ELSE**
 - Assign average density to all remaining segments
 - Break
 - **END**
- **END**
- Complexity : $O(n_i \times \log n_i)$ for each task
- Allow to dynamically add tasks online

What about performances?

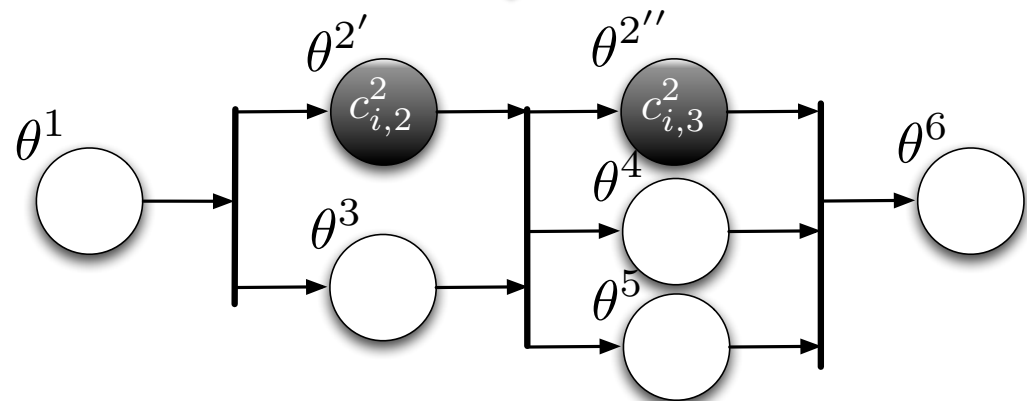


Extension to a More General Model of Multi-Threaded Tasks

- Threads shared by several segments
→ We reduce it to the previous problem

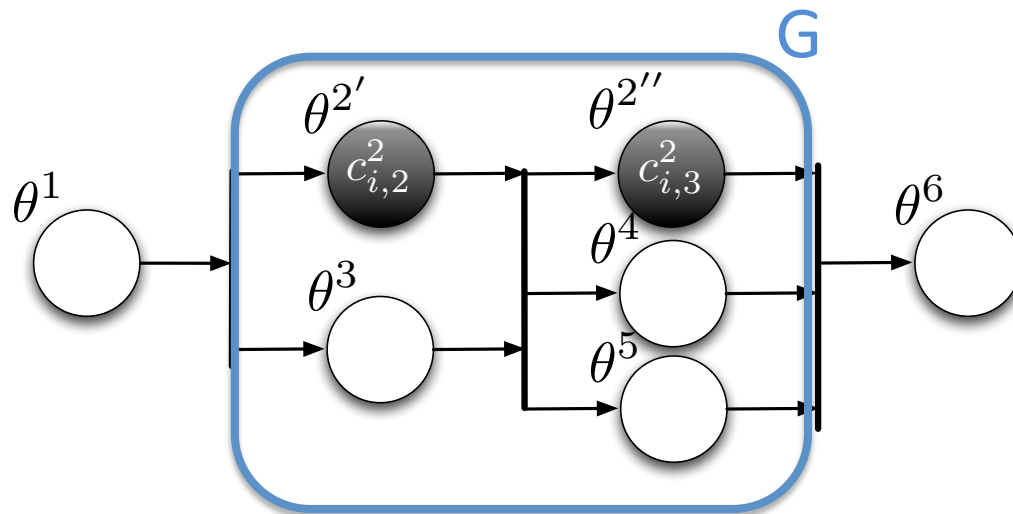


- The **Optimization** problem becomes **non-linear**



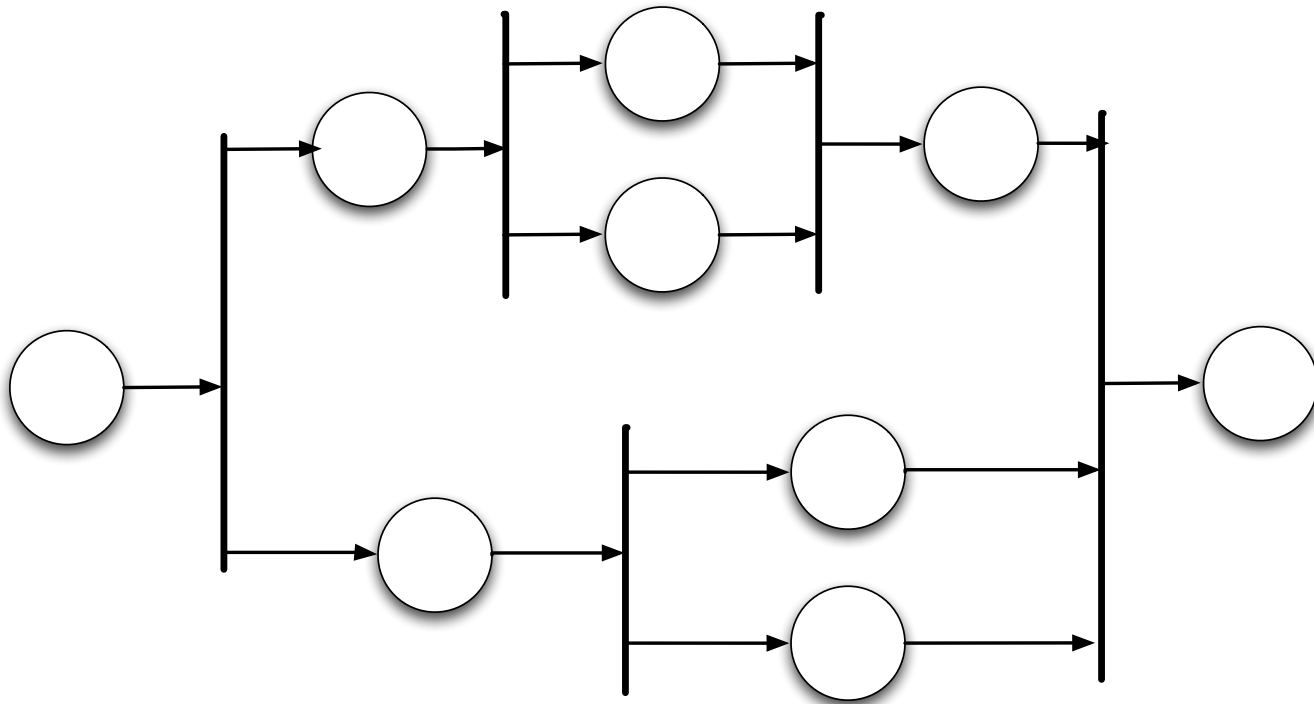
Extension to a More General Model of Multi-Threaded Tasks

- New difficulties:
 - More variables
 - segment deadline
 - repartition of WCET between segments
 - Decision taken in one segment strongly impacts other segments in G
- ➔ We need a tool taking into account the properties of many segments



Extension to a More General Model of Multi-Threaded Tasks

- Many parallel branches



Conclusions

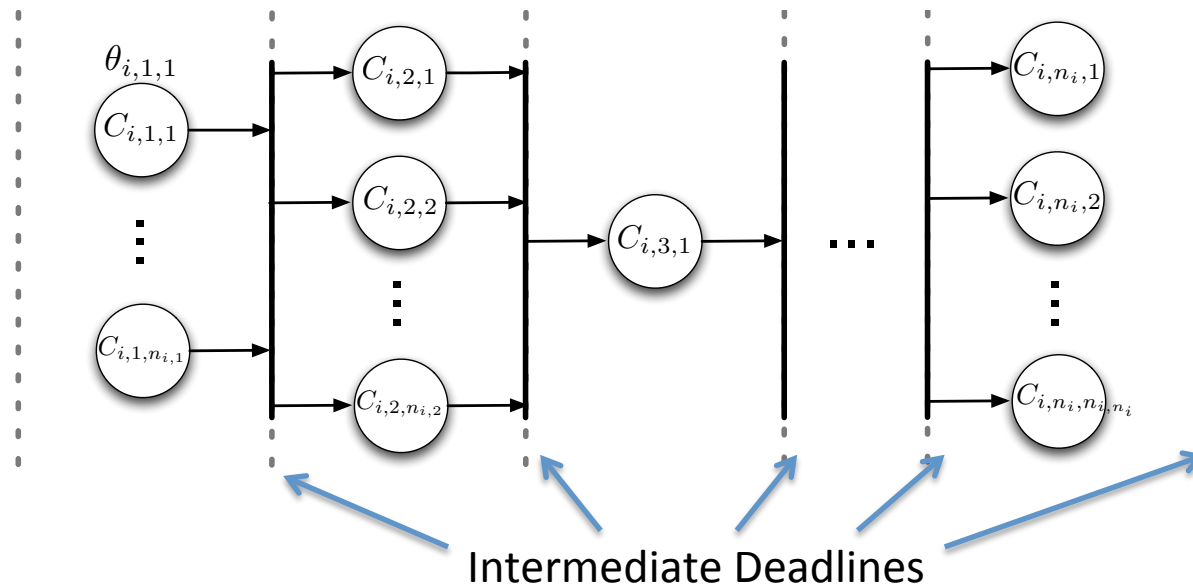
- Provide a way to « convert » a parallel task in a set of sequential task, by adding intermediate deadlines
- Optimal assignment (given we use intermediate deadlines)
- Low computational complexity ($O(n_i \times \log n_i)$ for each task)
- In average, we need 20% less processors than previous work
- Augmentation bound: 2
- Extension to multi-branch tasks

Questions?



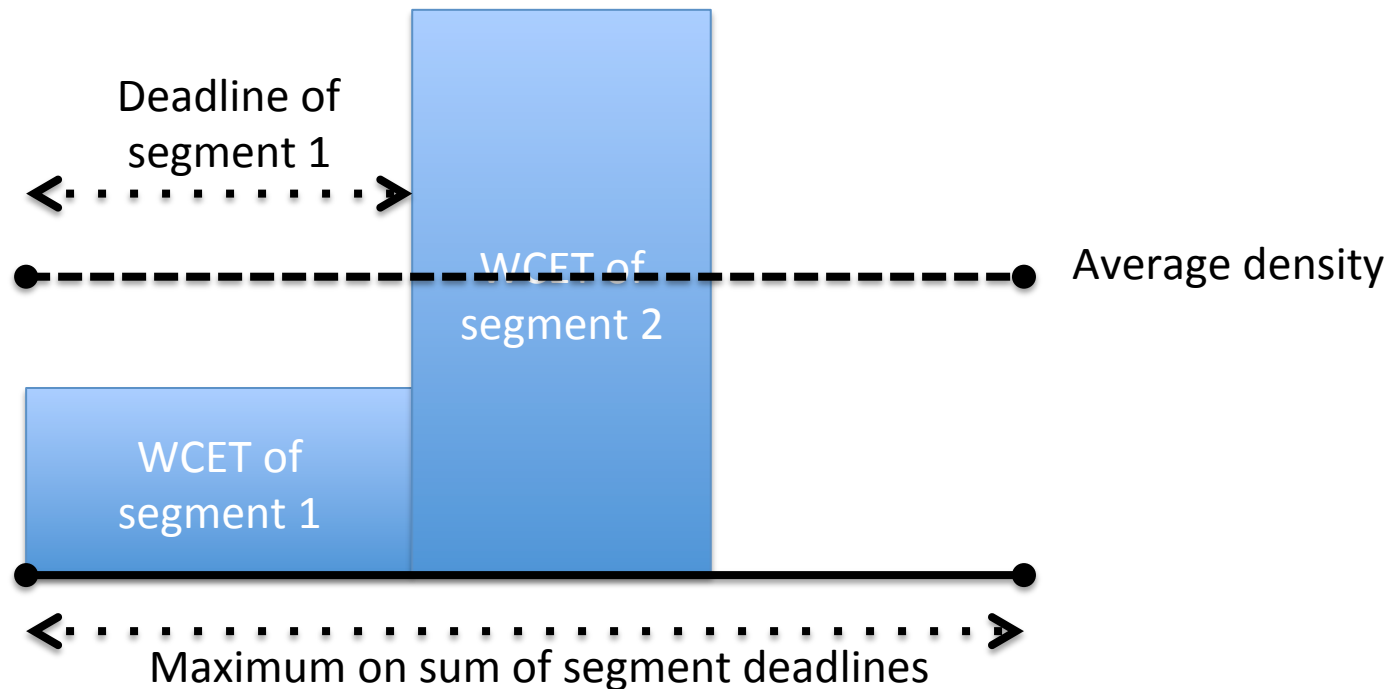
Manage the evolution of the task density by fixing the intermediate deadlines

- Number of threads varies → Task density changes with time
 - By imposing intermediate deadlines
- We can compute the density of each segment independently



Let us try to understand the optimal solution

- **Rule 2:** Minimize impact of segments with small densities



Let us try to understand the optimal solution

- **Rule 2:** Minimize impact of segments with small densities

