

A Framework to Construct Customized Harmonic Periods for Real-Time Systems

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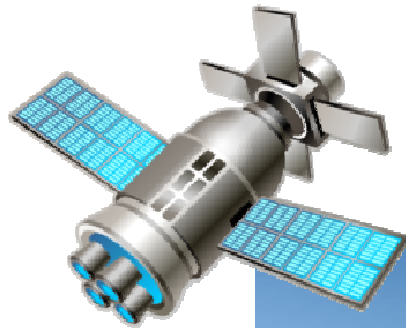
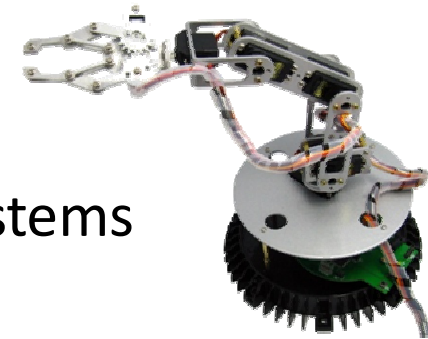
Mehdi Kargahi



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Motivations

- ▶ Periodic behavior appears in many real-time systems
 - It guarantees certain levels of safety and QoS

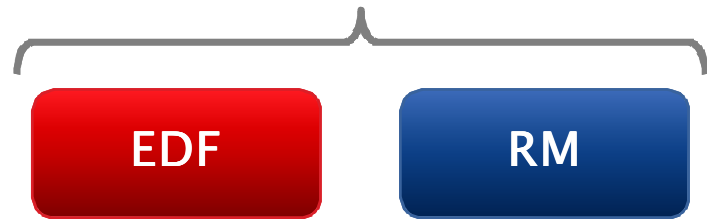
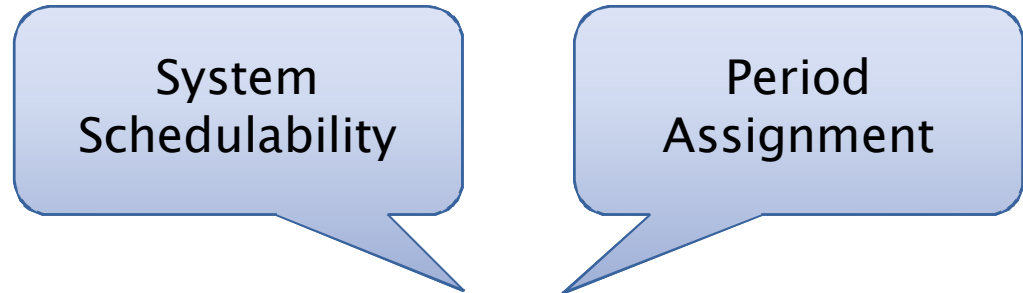
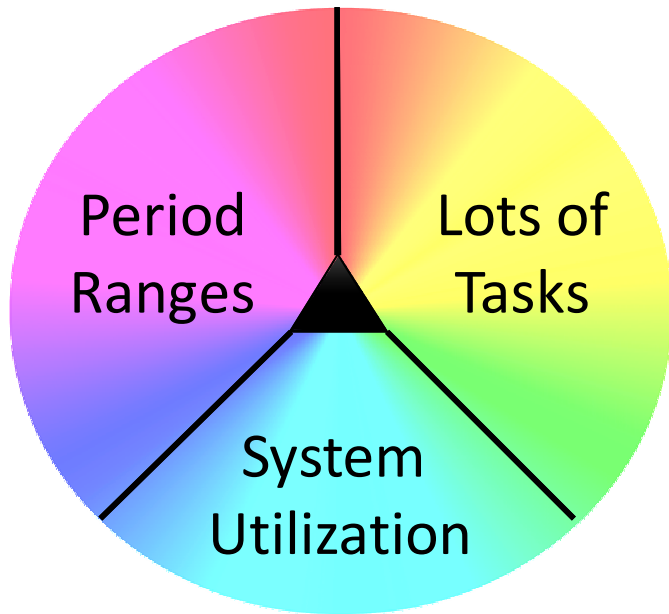


A lot of functionalities

Choice of periods and parameters

System Utilization

Motivations



- **Optimal**
- **Overheads**
- **No overhead**
- **Widely implemented**
- **Utilization Loss**

Approach: Finding Harmonic Periods

Optimally scheduled by **RM**

Exact **WCRT** has **polynomial-time** computational complexity

Harmonic Periods

Jitter is efficiently reduced

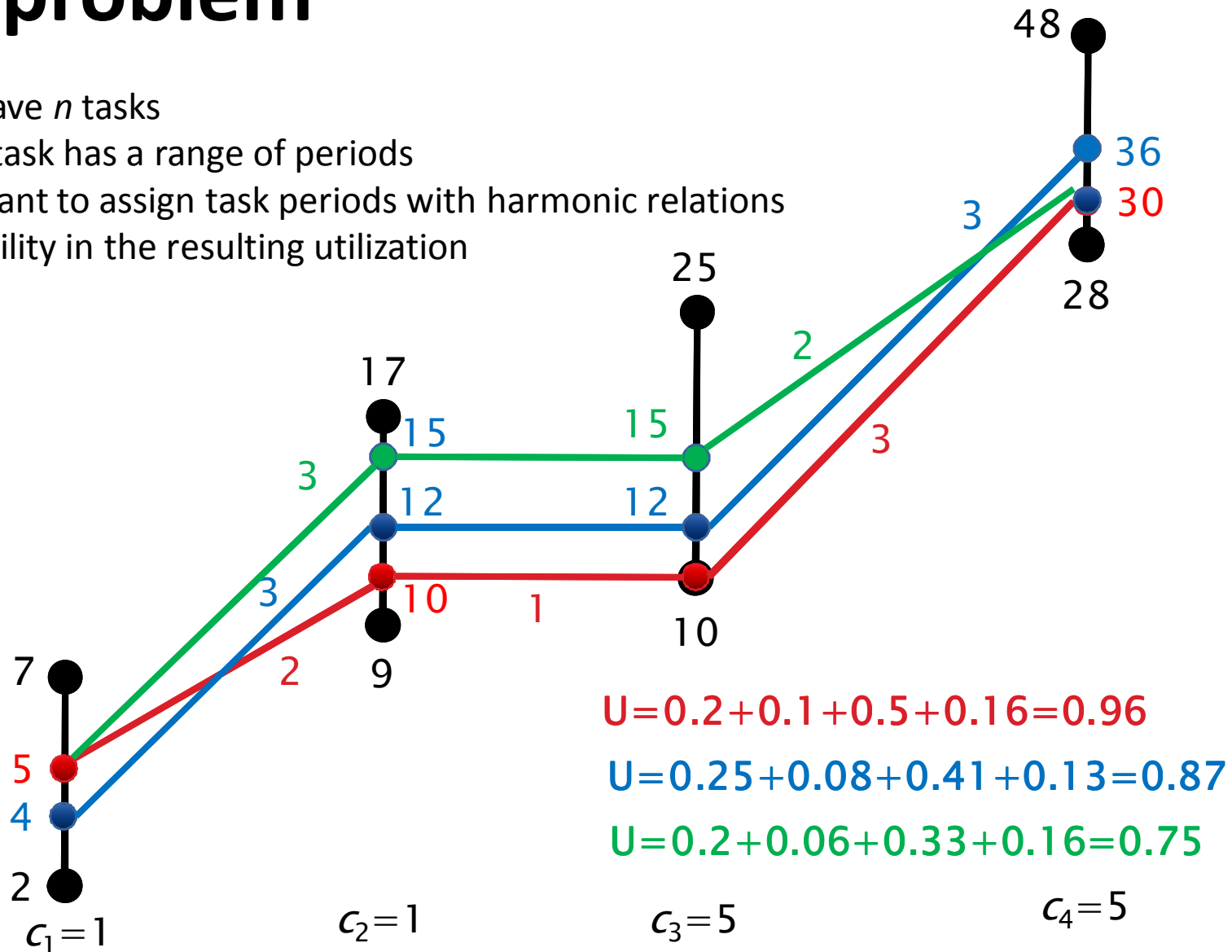
Small hyperperiod

Optimal non-preemptive scheduling

Wide **applicability** in industries:
Avionics, submarines, robotics

The problem

- We have n tasks
- Each task has a range of periods
- We want to assign task periods with harmonic relations
- Flexibility in the resulting utilization



Contributions

1. A **model** to describe harmonic relations between ranges
2. **Graph** representation of the model
3. Constructing **customized** harmonic relations by pruning the graph
4. Sufficient conditions for existence of a **linear-time solution**
5. **Utilization bound** of the resulting solutions



Agenda

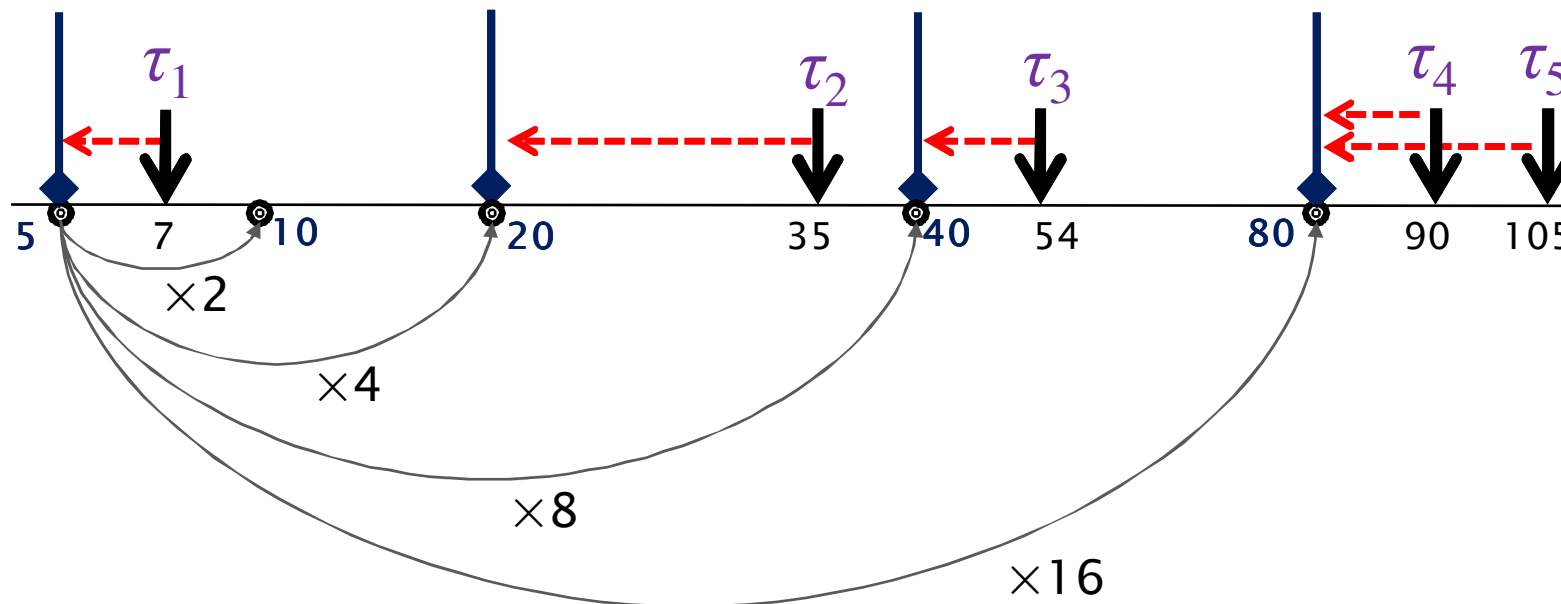
- ▶ Introduction and Motivations
- ▶ Related Work
- ▶ Finding Harmonic Relations
- ▶ Period Assignment
- ▶ Experimental Results
- ▶ Conclusion





Schedulability Analysis using Harmonic Periods

- ▶ Sr algorithm [Han 1997]





Assuming Period Range in Period Assignment

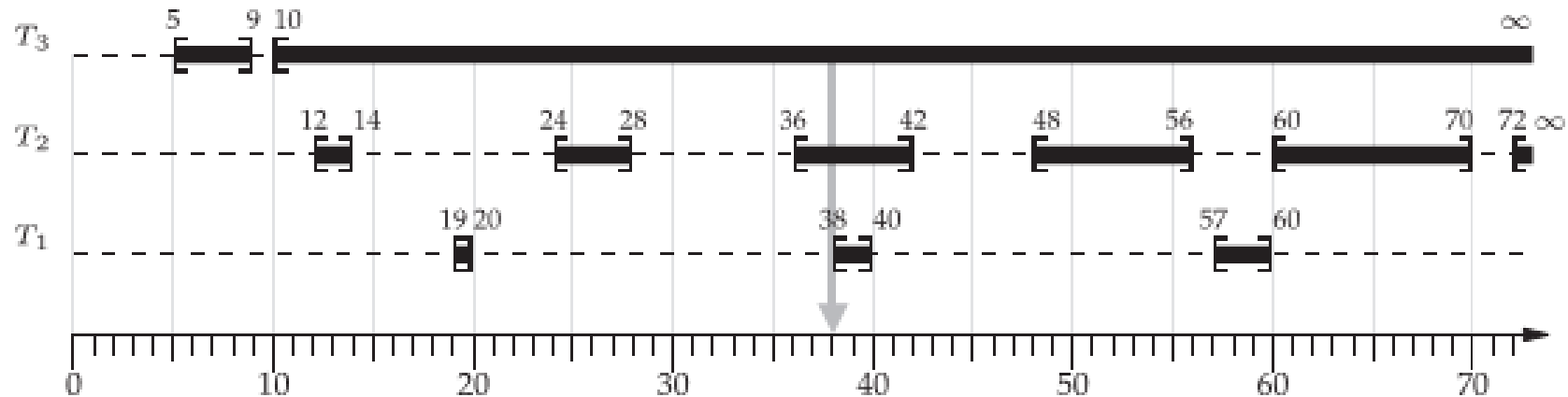
- ▶ Elastic task model
 - **Goal:** handling overloads
- ▶ Parameter assignment in control applications
 - **Goal:** improving quality of control
- ▶ **Difference:**
 - No utilization bound for the solution
 - None for harmonic periods



Minimizing Hyperperiod

▶ Ripoll 2013

- Given Period Ranges, they find the shortest intersection between integer multipliers of the period ranges among all tasks in the system



Agenda

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- ▶ **Finding Harmonic Relations**
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System Model

- ▶ Periodic task set
 - A period range for each task
 - Implicit deadline
 - Tasks are indexed according to the T_i^{min}
 - **The goal** is to assign period T_i to each task τ_i

$$\tau = \{\tau_1, \tau_2, \dots, \tau_n\}$$

$$\tau_i: (C_i, T_i^{min}, T_i^{max})$$

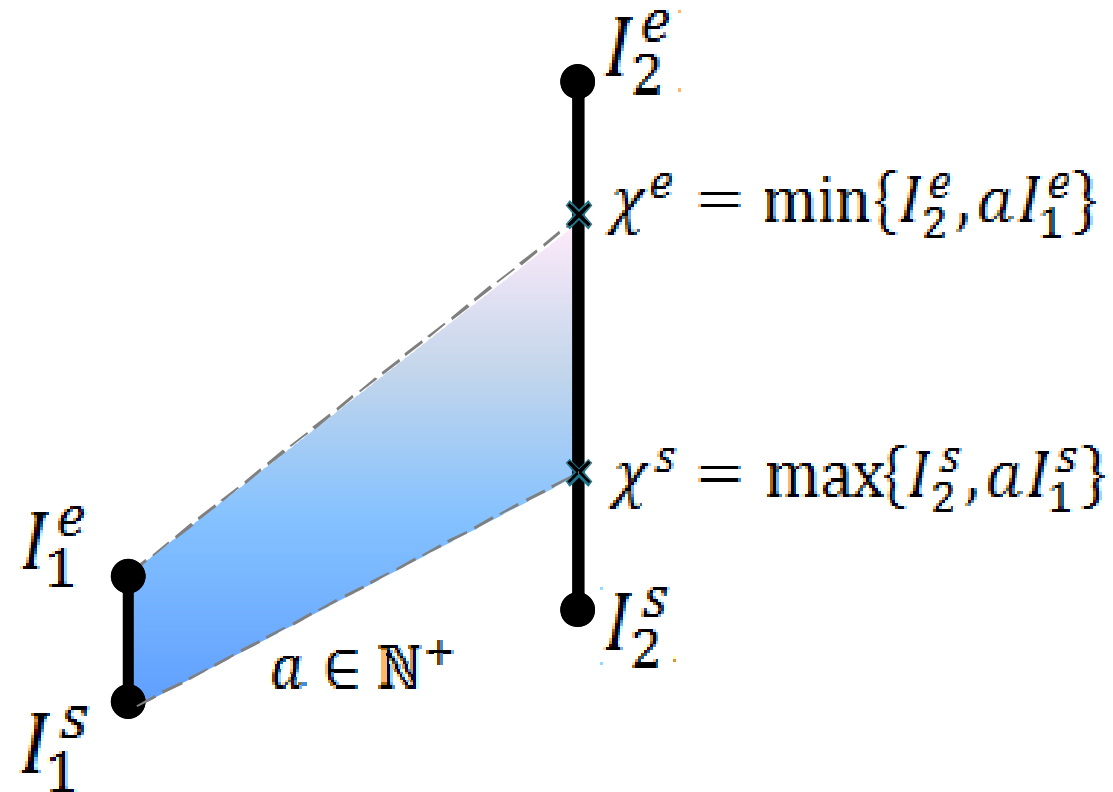
- An interval is denoted by





Projected Harmonic Zone

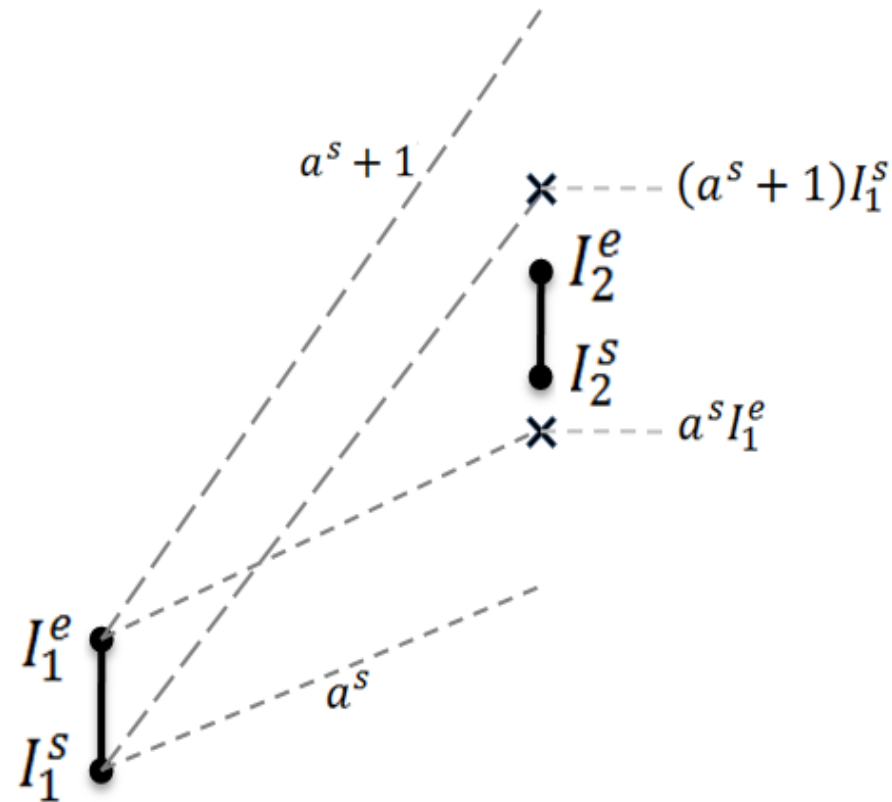
$$\chi_{I_1 \rightarrow I_2}^a$$





Necessary Condition for Projected Harmonic Zones

$$a^s = \left[\begin{array}{c} I_2^s \\ I_1^e \end{array} \right]$$





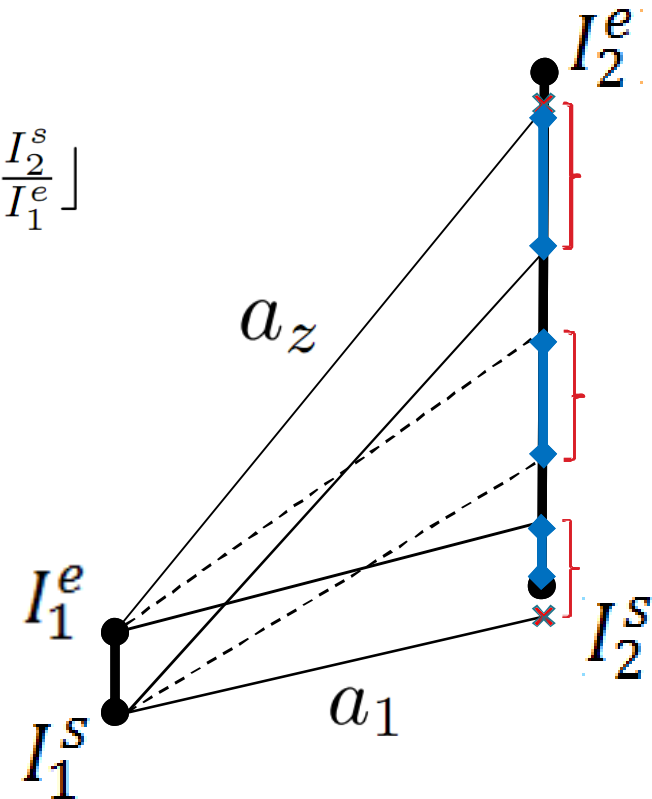
Harmonic Multipliers

$$a_1 = \lfloor \frac{I_2^s}{I_1^e} \rfloor + 1 \quad \text{If } \lfloor \frac{I_2^s}{I_1^e} \rfloor \in \mathbb{N}, a_1 = \lfloor \frac{I_2^s}{I_1^e} \rfloor$$

$$a_2 = a_1 + 1$$

...

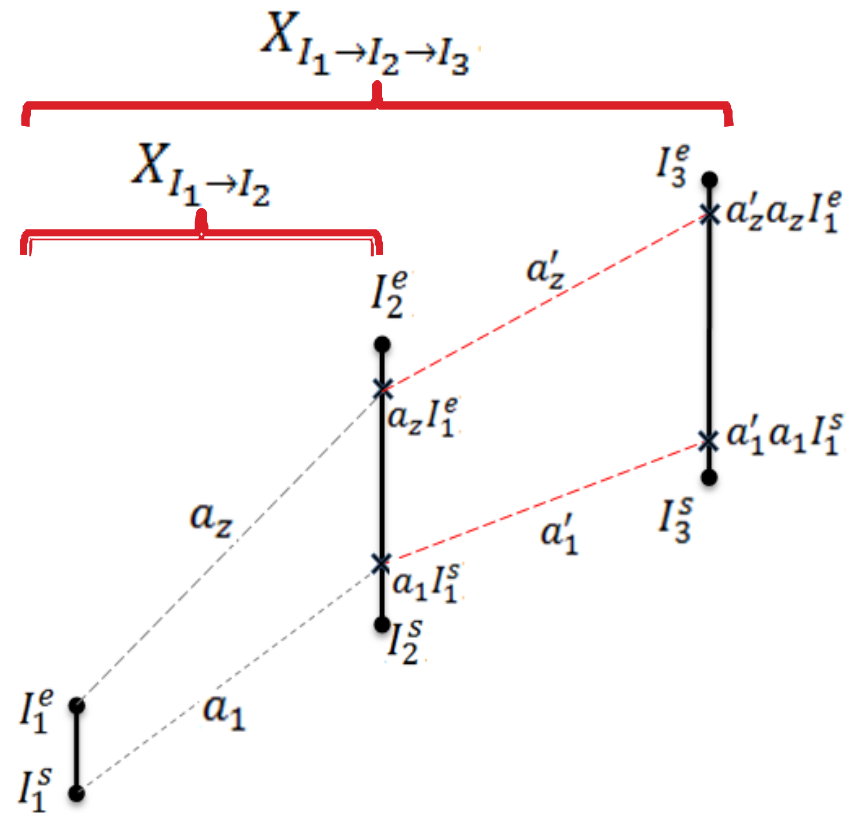
$$a_z = \lfloor \frac{I_2^e}{I_1^s} \rfloor$$



These are the only possible multipliers which can exist

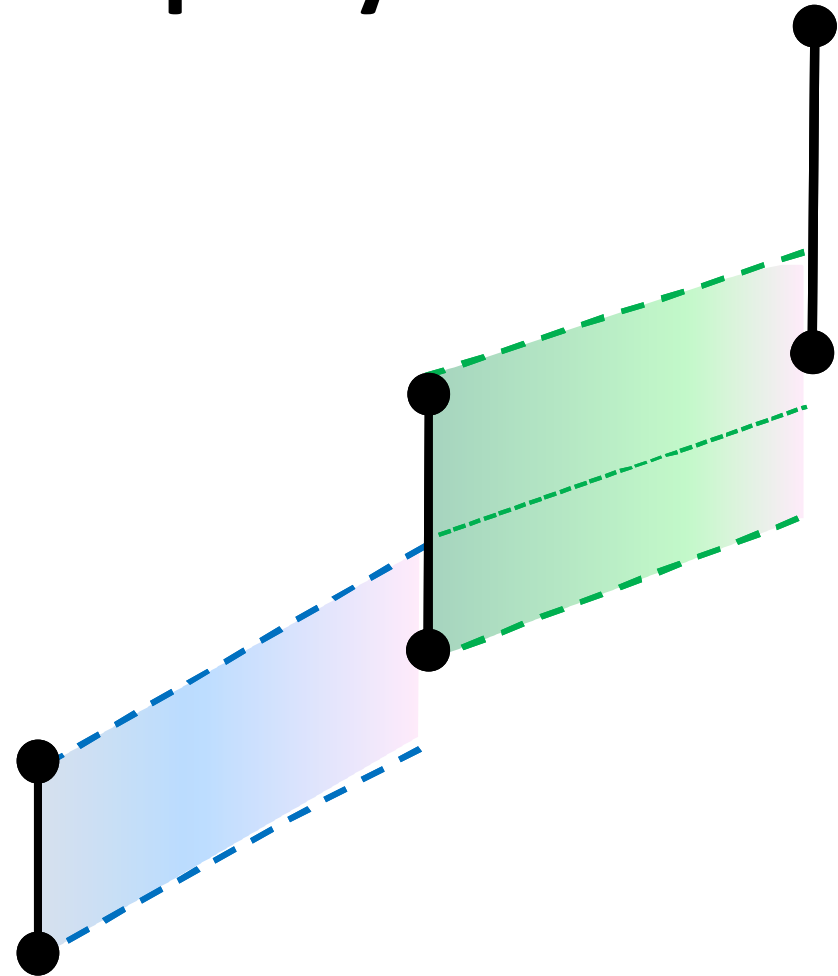
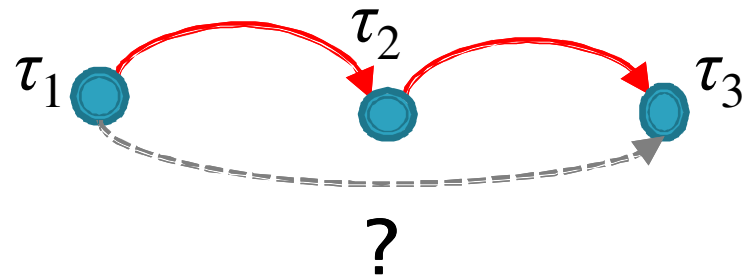


Harmonic Relations of More Tasks



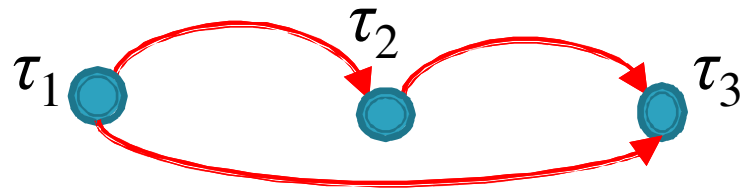


Transitive Closure Property

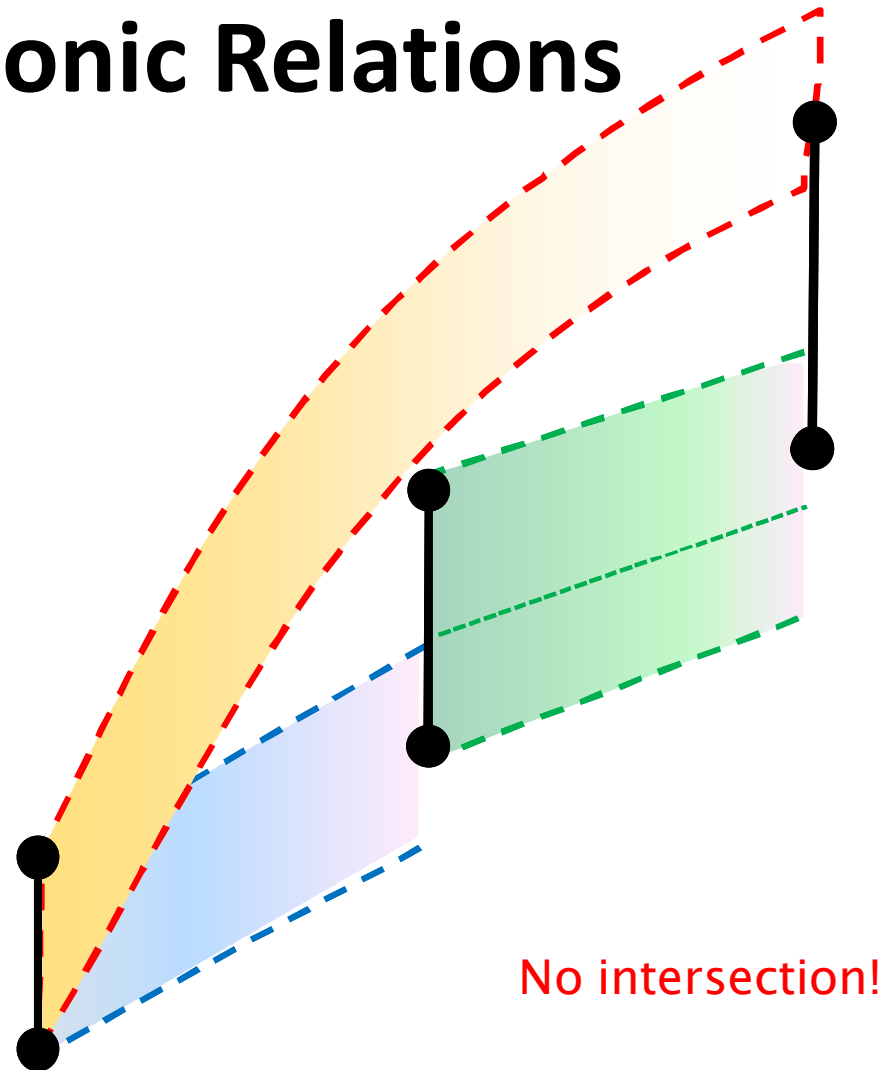




Existence of Harmonic Relations

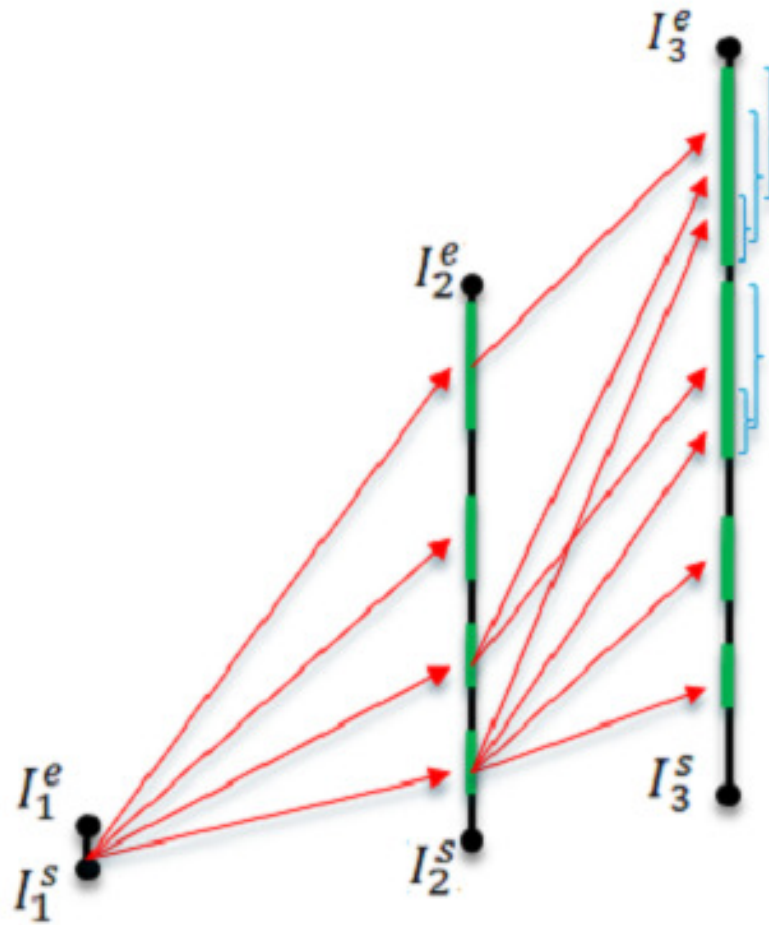


But it does not imply that you have a harmonic relation between all of tasks!



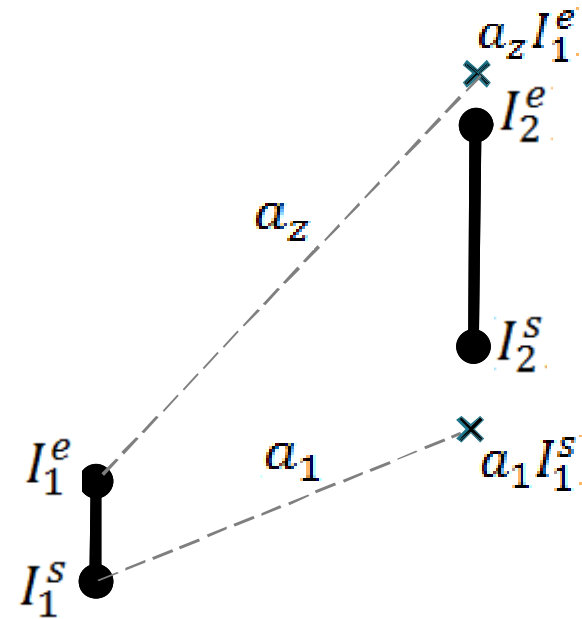
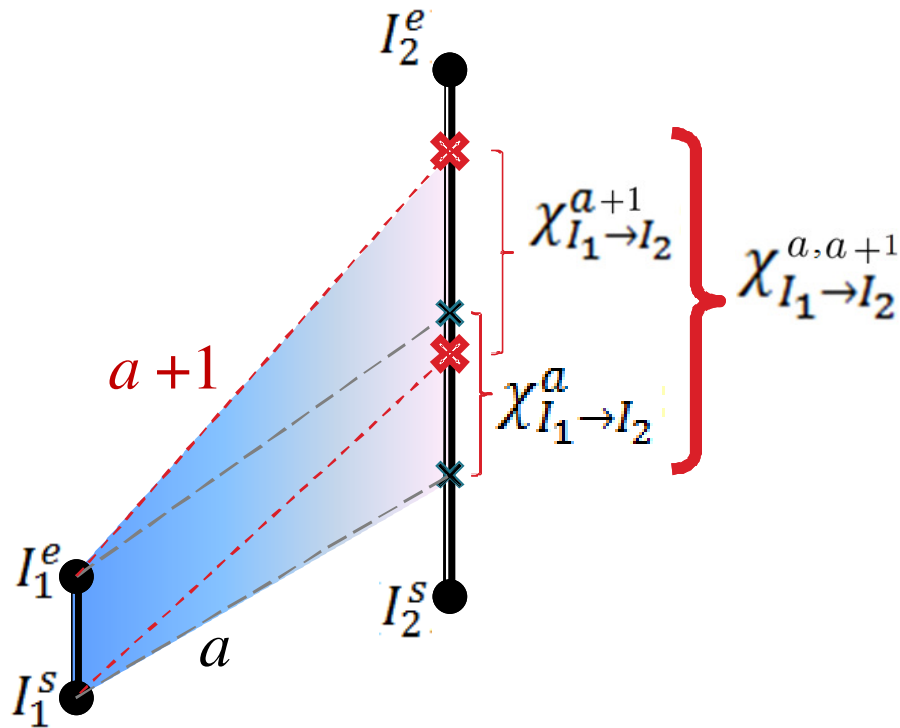


Harmonic Relations of More Tasks





Continuous Harmonic Zones



Tight Harmonic Relation



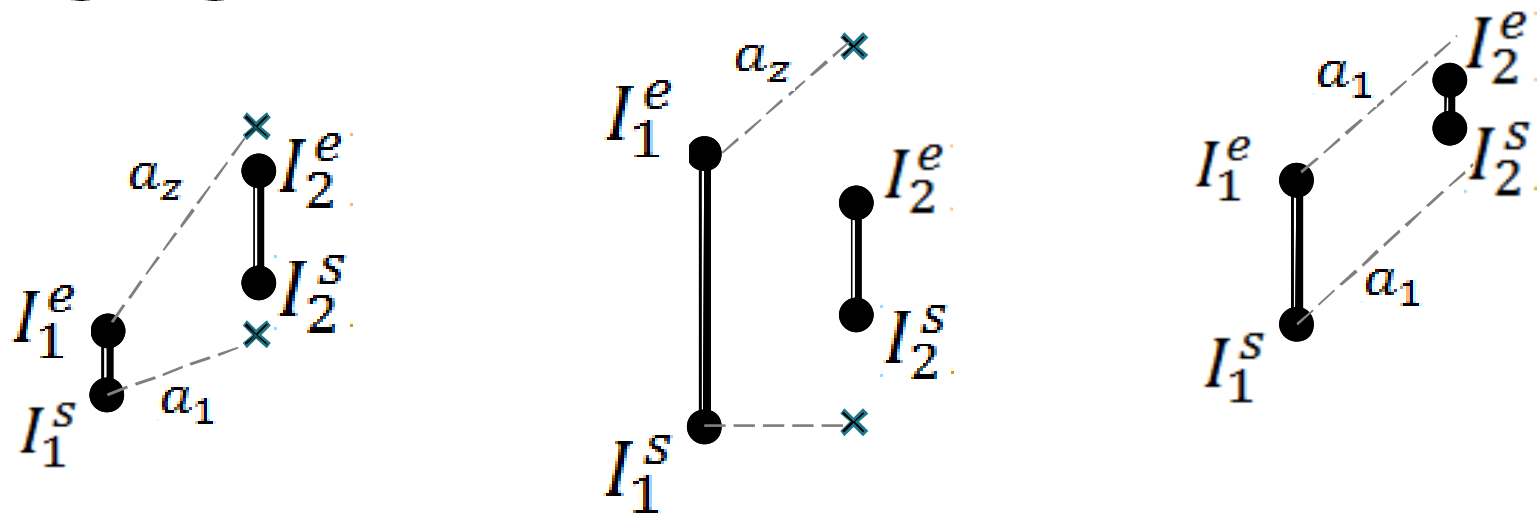
Necessary Conditions for Tight Harmonic Relations

$$a_1(I_1^e - I_1^s) \geq I_1^s$$

$$I_2^e \leq I_1^e$$

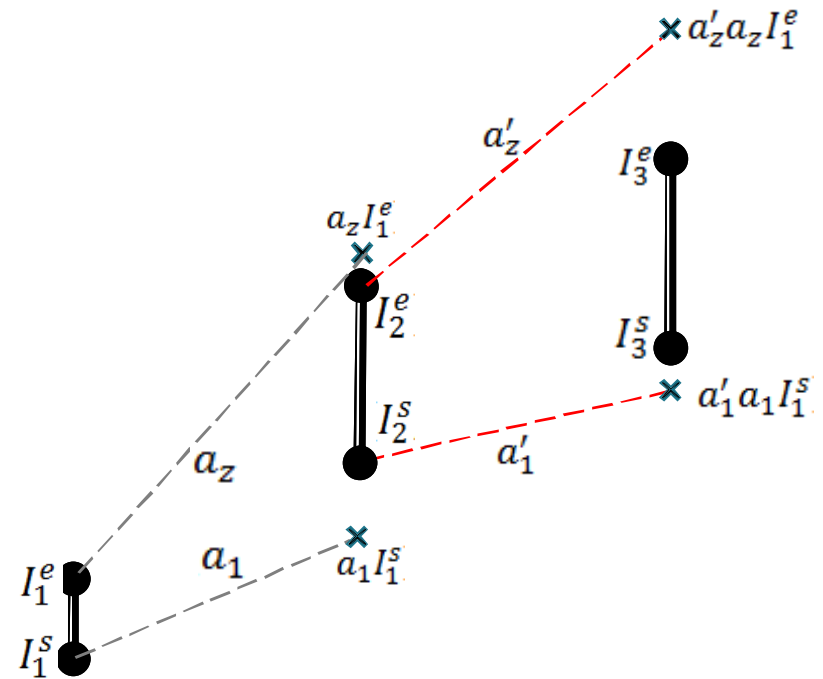
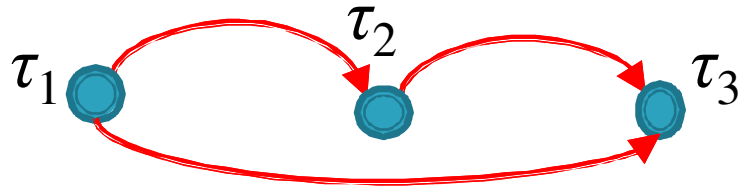
$$a_1 I_1^s \leq I_2^s \leq I_2^e \leq a_1 I_1^e$$

$$\frac{I_1^s I_1^e}{I_1^e - I_1^s} \leq I_2^s$$





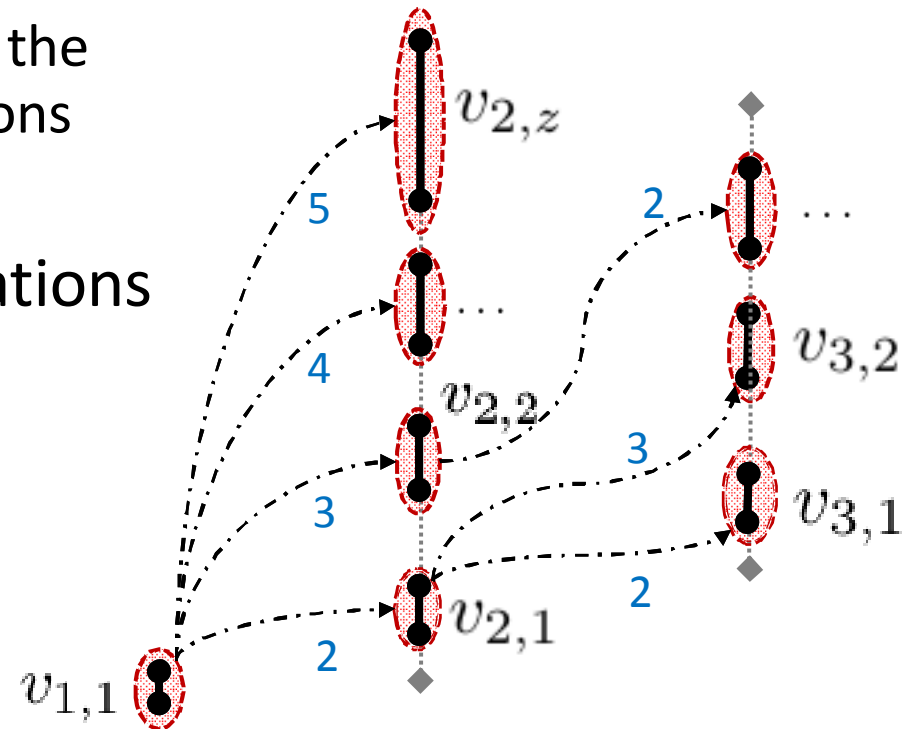
Transitive Closure Property in Tight Harmonic Relations





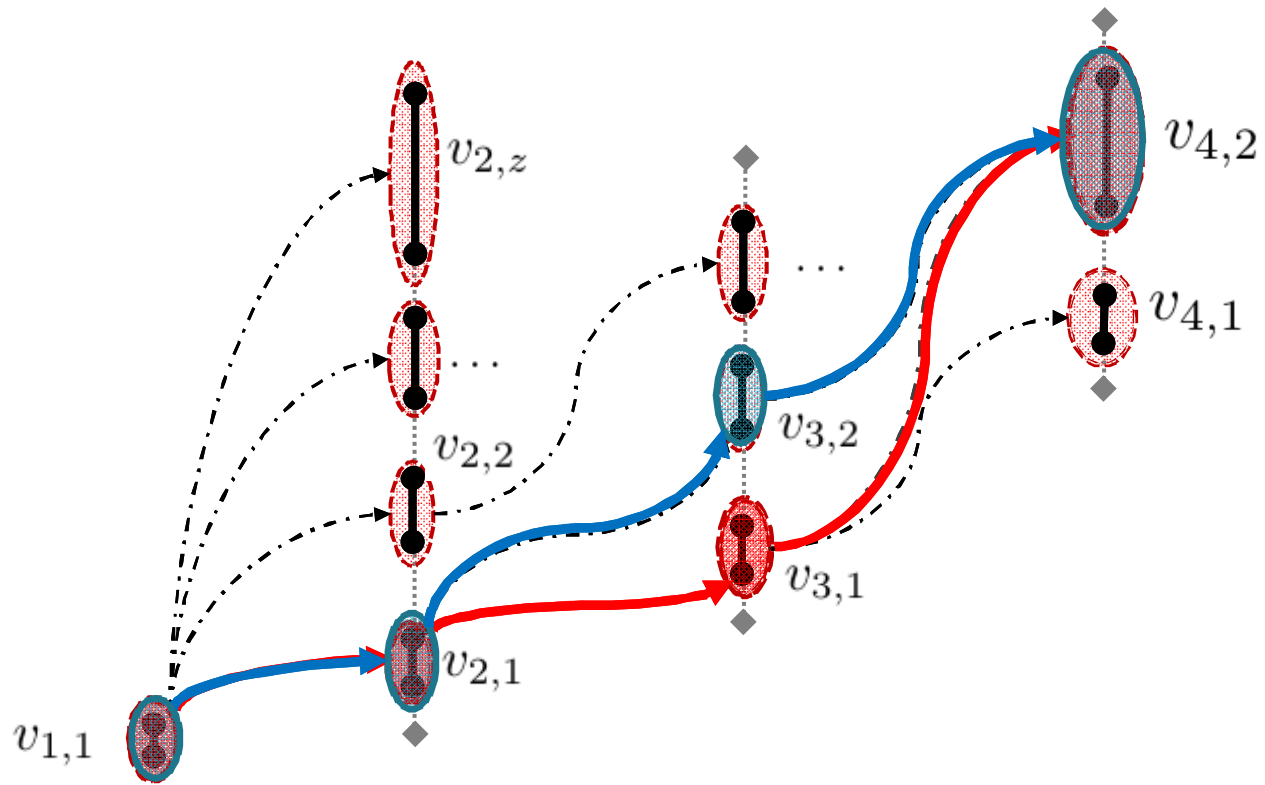
Graph Representation

- ▶ GCA algorithm
 - A BFS algorithm to construct the graph of the harmonic relations
- ▶ Customized Harmonic Relations by Pruning the Graph





Each Path is a Solution

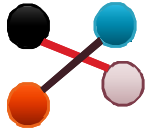


**Linear-time computational complexity
for tight harmonic relations**

Agenda

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- ▶ **Period Assignment**
- ▶ Experimental Results
- ▶ Conclusion

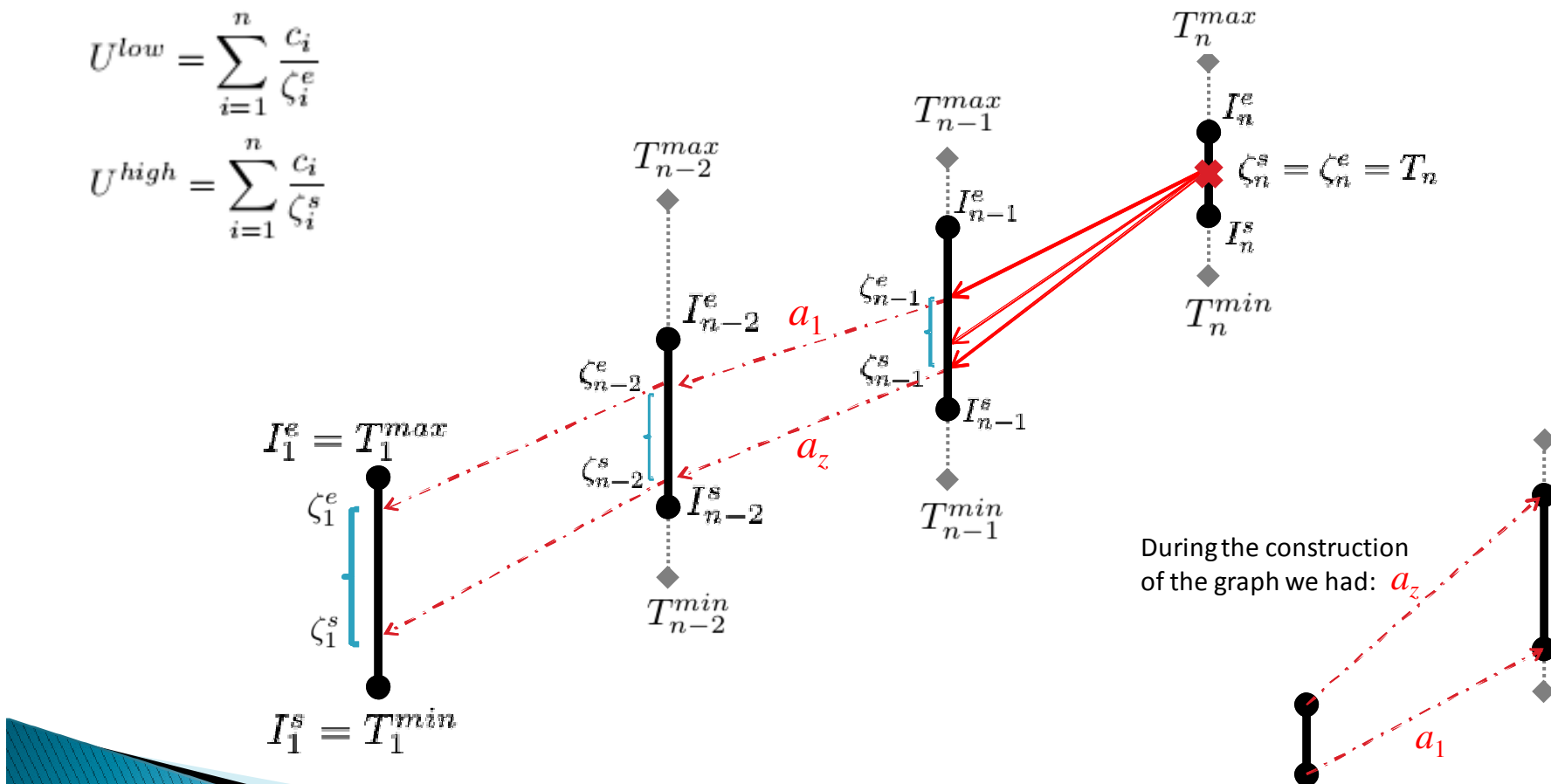


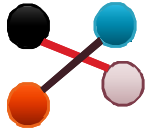


Utilization Bound of a Solution

$$U^{low} = \sum_{i=1}^n \frac{c_i}{\zeta_i^e}$$

$$U^{high} = \sum_{i=1}^n \frac{c_i}{\zeta_i^s}$$

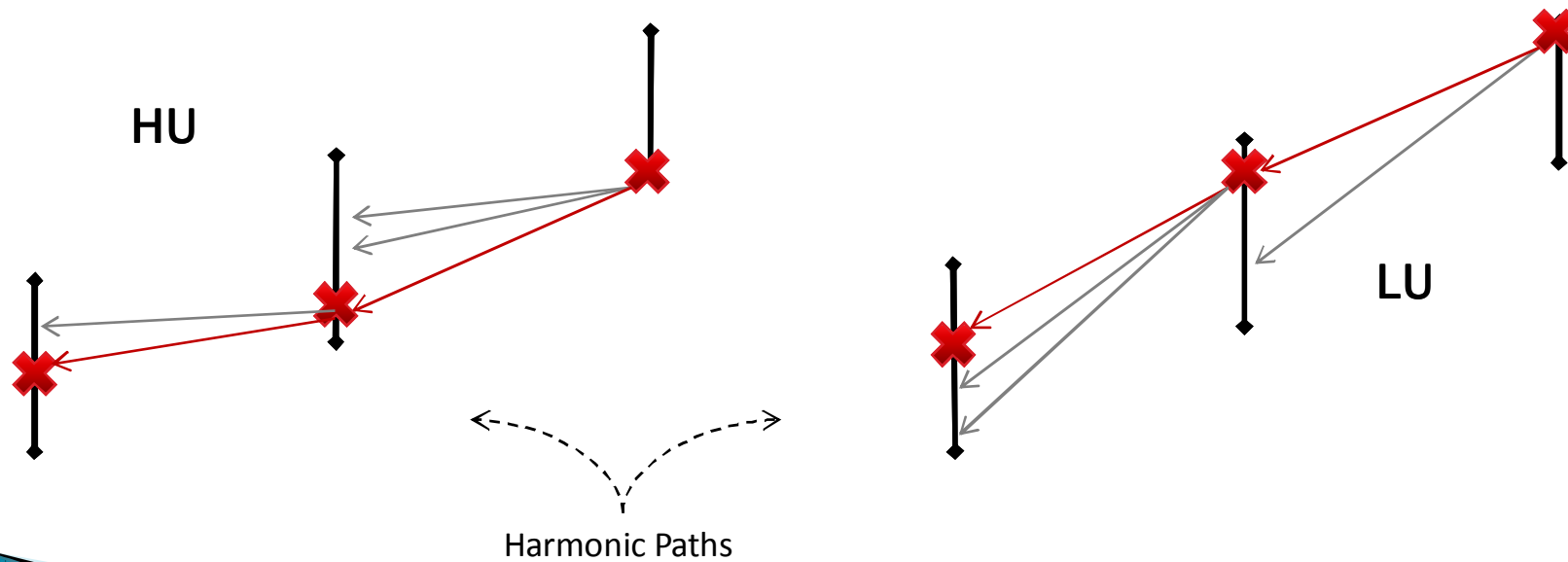




Period Assignment

▶ Heuristic Algorithms

- Period assignment with high and low utilization (**HU** and **LU**)
- They might not provide the highest or the lowest utilization.



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Experiments

▶ Algorithms

- **Sr** [Han 1997]
- Optimal period assignment: searches all possible solutions to find maximum feasible utilization (**Optimal**)
- Period assignment with High Utilization (**HU**)
- Period assignment with Low Utilization (**LU**)
- **Lower Bound** of the utilization
- **Upper Bound** of the utilization

LU and HU are heuristic



Experiments

▶ Workload Model

- Based on random period ranges (not necessarily harmonic) [Ripoll 2013]

$$T_i^{max} = rand[100, 5000]$$

$$T_i^{min} = T_i^{max} (1 - \sigma)$$

$$\sigma \in [0.3, 0.8]$$

- More experiments in the paper

▶ Target measure

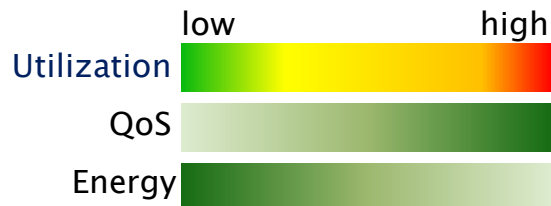
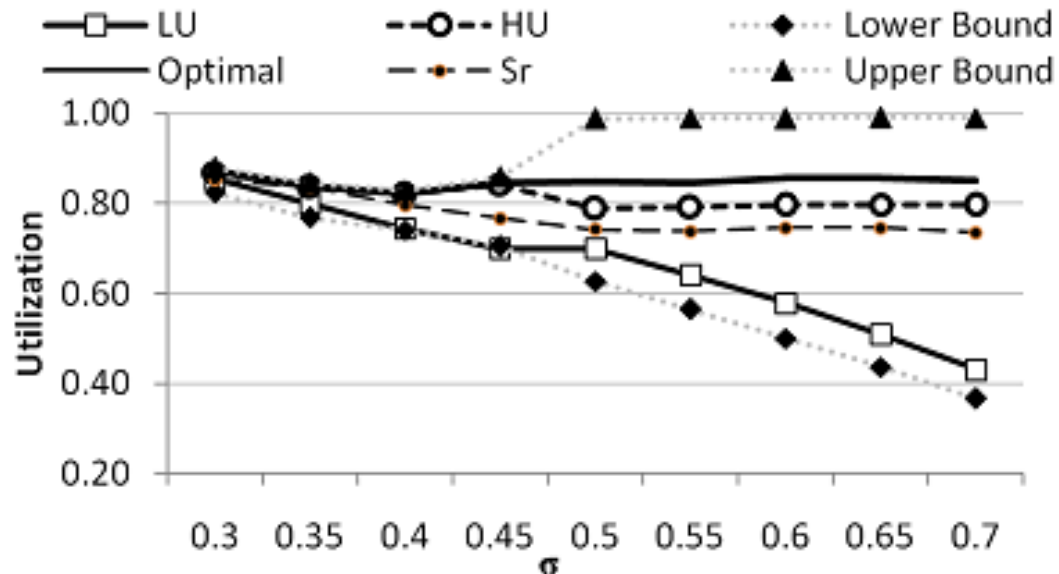
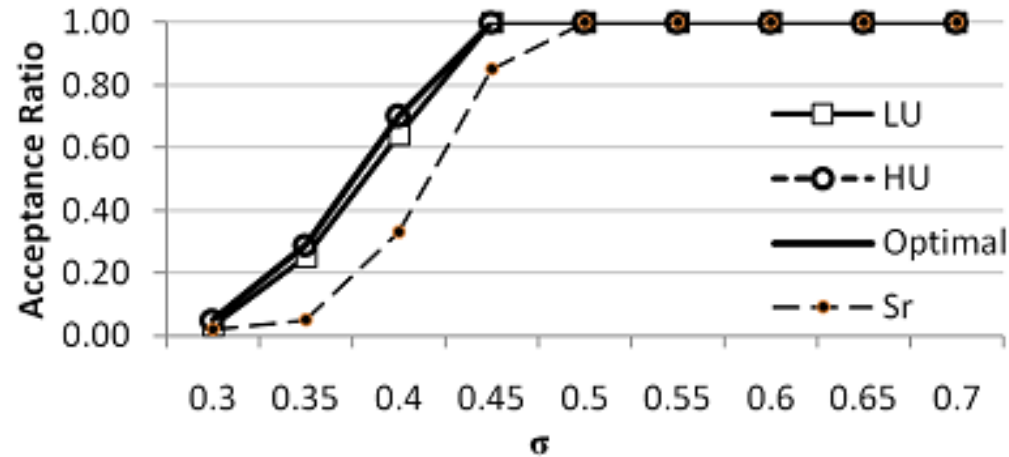
- **Acceptance Ratio**: Ratio of accepted fully harmonic task sets to all generated task sets
- **Utilization**



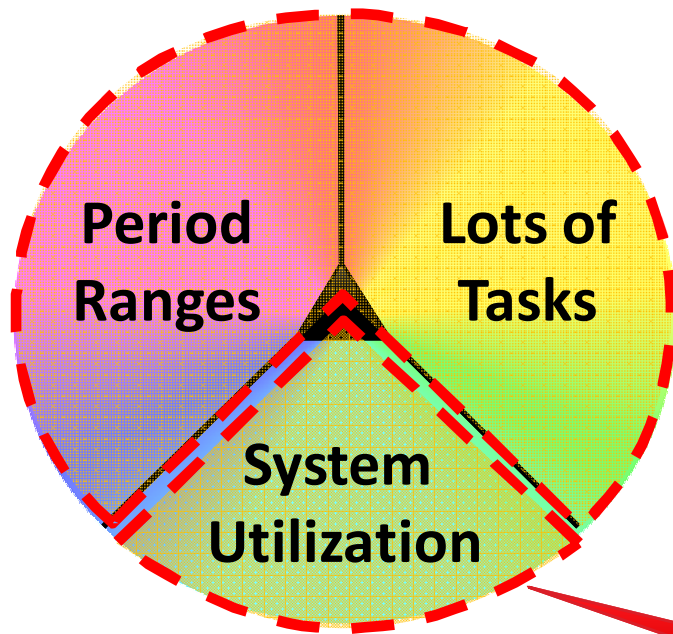
Experiments

Random Tasks with Workload Model [Ripoll13]

σ shows how wide are period ranges.



Conclusions



Harmonic Periods

A Model

A Graph

Sufficient Conditions of
Linear-Time Solution

Customized Harmonic Relations
by Pruning the Graph

Utilization Bound of
Each Resulting Solution

Future Works

- ▶ The error bound of **period rounding**
- ▶ Period assignment algorithm with **user defined utilization**
- ▶ **Slack-aware** graph pruning algorithm
 - Provides sufficient conditions for optimal scheduling of non-preemptive harmonic tasks





Questions

Thank you