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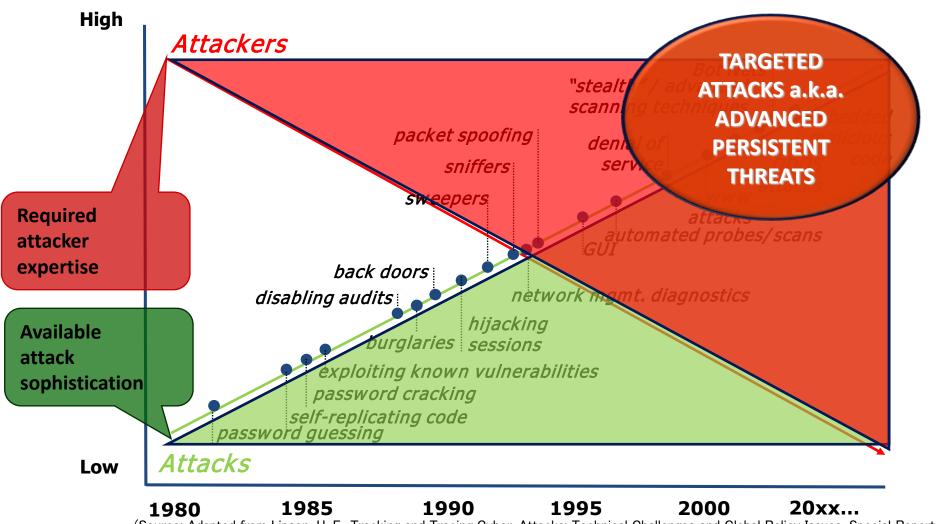
SnT - CritiX

Sustainable Security & Safety: Challenges and Opportunities

Andrew Paverd, <u>Marcus Völp</u>, Ferdinand Brasser, Matthias Schunter, N. Asokan, Ahmad-Reza Sadeghi, Paulo Esteves-Veríssimo, Andreas Steininger, Thorsten Holz Intel Collaborative Research Center – Collaborative Autonomous Resilient Systems marcus.voelp@uni.lu



Attack sophistication vs. attacker expertise



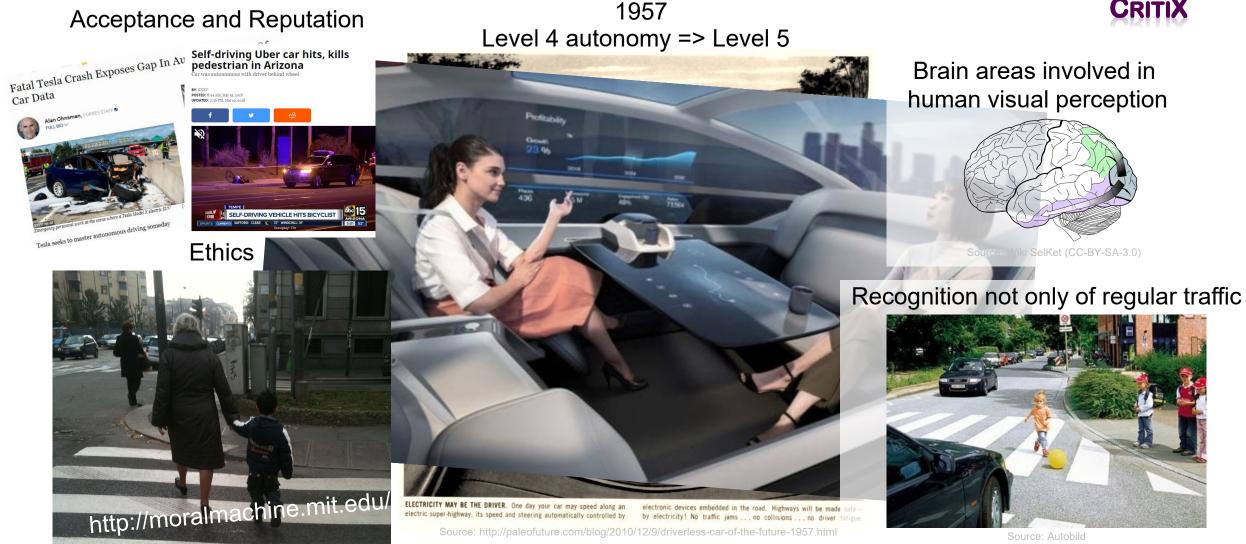
(Source: Adapted from Lipson, H. F., Tracking and Tracing Cyber-Attacks: Technical Challenges and Global Policy Issues, Special Report CMS/SEI-2002-SR-009, November 2002. (CERT)

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Autonomous driving – the next complexity milestone





Autonomous driving – the next complexity milestone



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Autonomous driving – the next complexity milestone securitvandtrust.lu iniversité du CRITIX Functionality vs. Complexity localization Components associated with physical control of the vehicle triangumotion control lation prediction Components associated with safety obstacle detection Components associated with path planning entertainment and convenience neural network stereo smooth and flocks Bavesian / based Monte Carlo sharp trajectories 10.0 collision avoidance sensor fusion lane / sign detection low level Image credit: Mercedes-Benz neural feature 20 1 network fusion Museum (as cited in Computer video History Museum, 2011) based Slide from Intel ADG

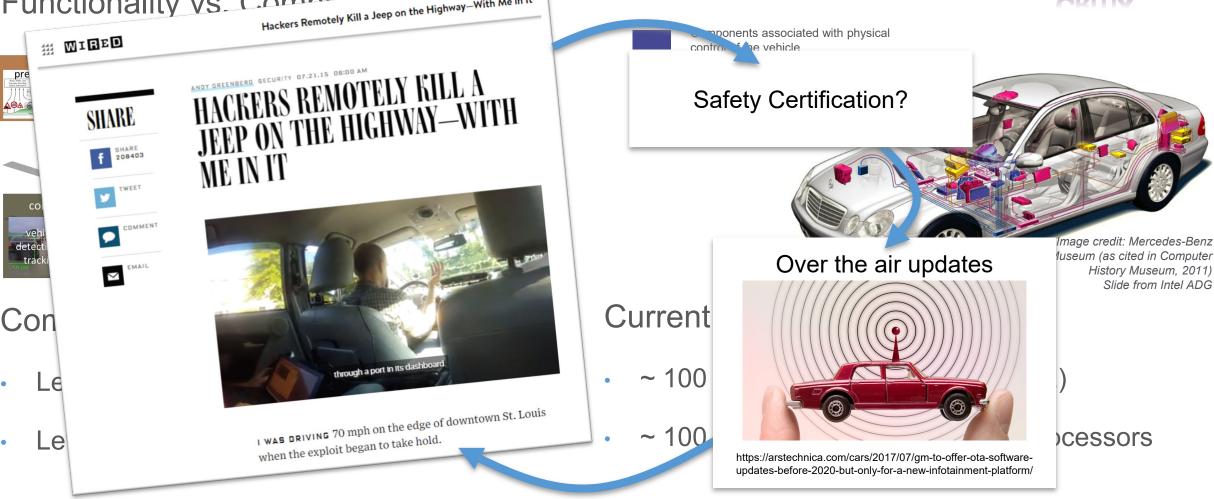
Complexity of autonomous driving:

- Level 3: 300 MLOC (human supervision)
- Level 5: 1 BLOC+ ?

Current Cars:

- ~ 100 MLOC (30 MLOC multimedia)
- ~ 100 ECUs

Autonomous driving – the next complexity milestone securitvandtrust.lu mmi In iniversité du CRITIX Functionality vs. Complexit Hackers Remotely Kill a Jeep on the Highway—With Me in It ponents associated with physical # WIRED control the vehicle HACKERS REMOTELY KILL A JEEP ON THE HIGHWAY—WITH pre Safety Certification? SHARE SHARE 208403



Autonomous driving – the next complexity milestone securitvandtrust.lu CRITIX Functionality vs. Completit Hackers Remotely Kill a Jeep on the Highway—With Me in It conents associated with physical # WIRED he vehicle contro ANDY GREENBERG SECURITY 07.21.15 06:00 AM pre TA OFFRS REMOTE Safety Certification? SHARE We need systems to survive faults and intrusions SHARE 208403 TWEET throughout their lifetime! (for cars: avg. lifetime of 11.6 year on US roads) COMMENT 0 Image credit: Mercedes-Benz detect luseum (as cited in Computer EMAIL \sim History Museum, 2011) [IHS Markit Report '18] Slide from Intel ADG Con through a port in its dashboai 100 \sim Le I WAS DRIVING 70 mph on the edge of downtown St. Louis 100 when the exploit began to take hold.)cessors Le https://arstechnica.com/cars/2017/07/gm-to-offer-ota-softwareupdates-before-2020-but-only-for-a-new-infotainment-platform/

Challenges

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ownership changes

- How to securely inform the system about the change in ownership, without opening a potential attack vector?
- How to erase sensitive data during transfer of ownership, without allowing the previous owner to later erase data of the new owner?

maintainer changes

- How can a system decide that it is no longer maintained?
- How should an unmaintained system behave?

environmental changes

• How to tolerate failure of subsystems due to unforeseeable threats?

subsystem failures

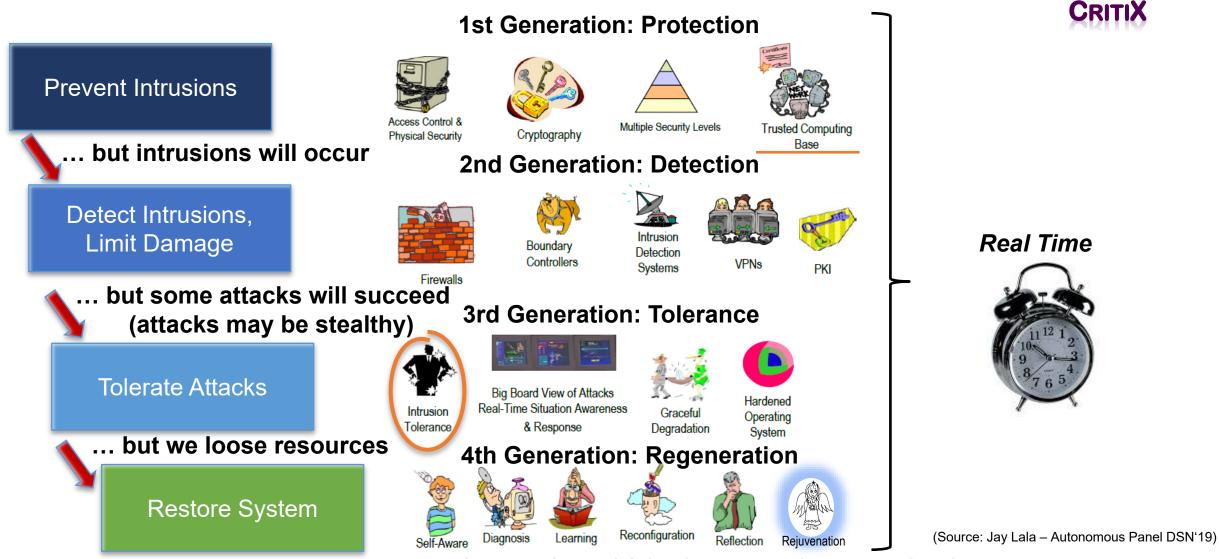
- How can we assert the sustainability of emerging material circuits, without at the same time giving adversaries the tools to stress and ultimately break these circuits?
- How to prevent the leakage of sensitive information from a compromised subsystem?
- How to securely re-provision a subsystem after all secrets have been leaked?

requirement changes

- How to retroactively change the designed security, privacy, and/or safety guarantees of a system?
- How can a system be extended and adapted to meet new expectations after deployment?
- Howto determine whether a deployed system will retain its safety and security guarantees for an even longer lifetime?

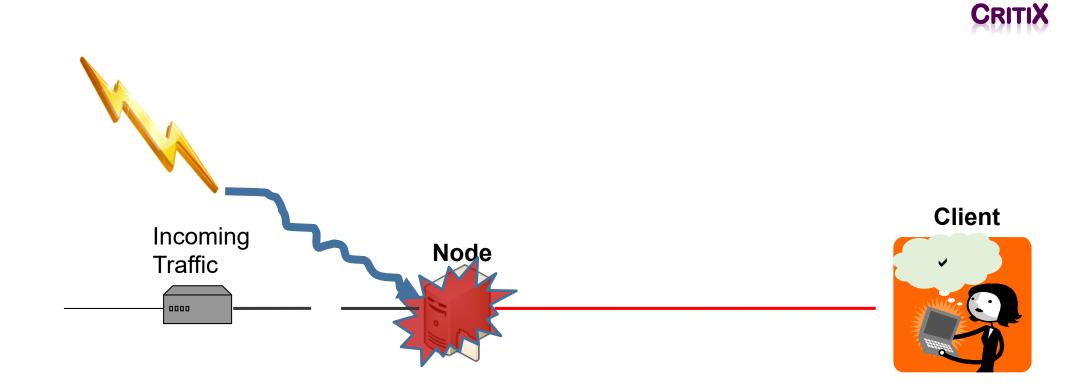


Cyber Resilient Architectures



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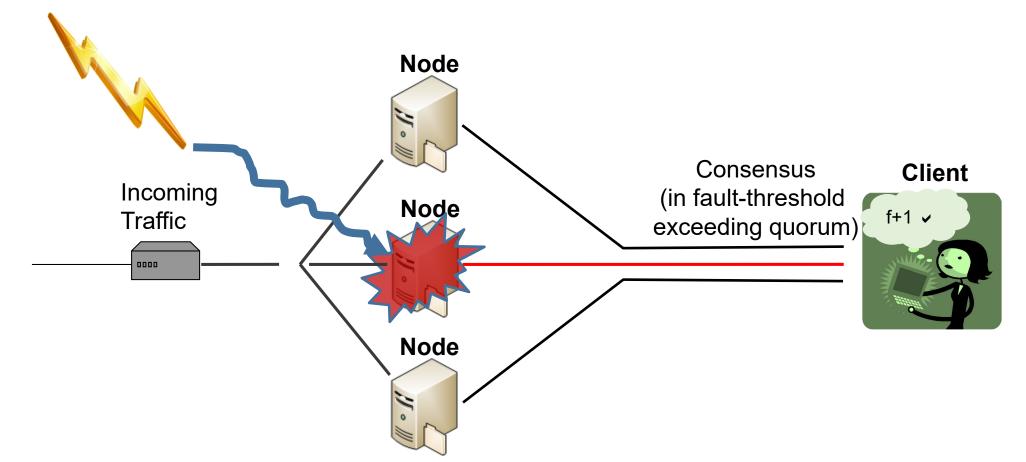
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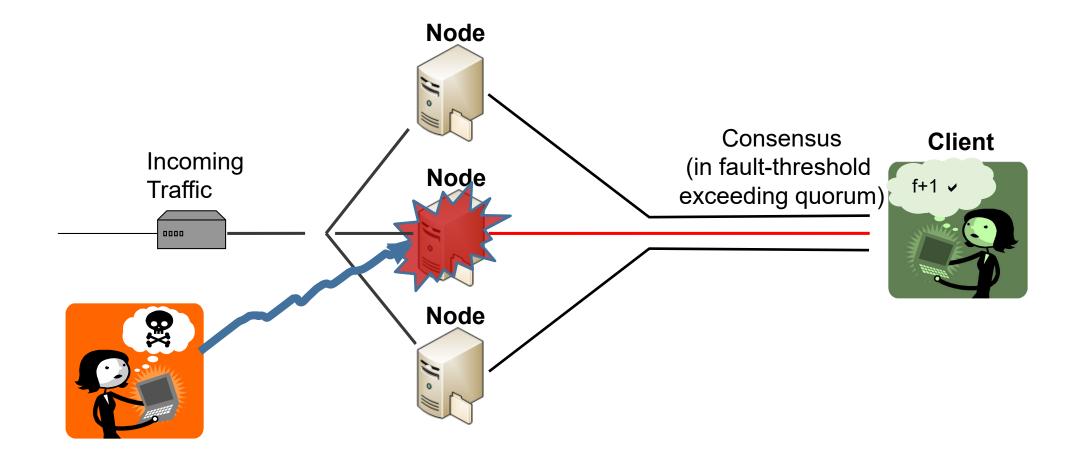
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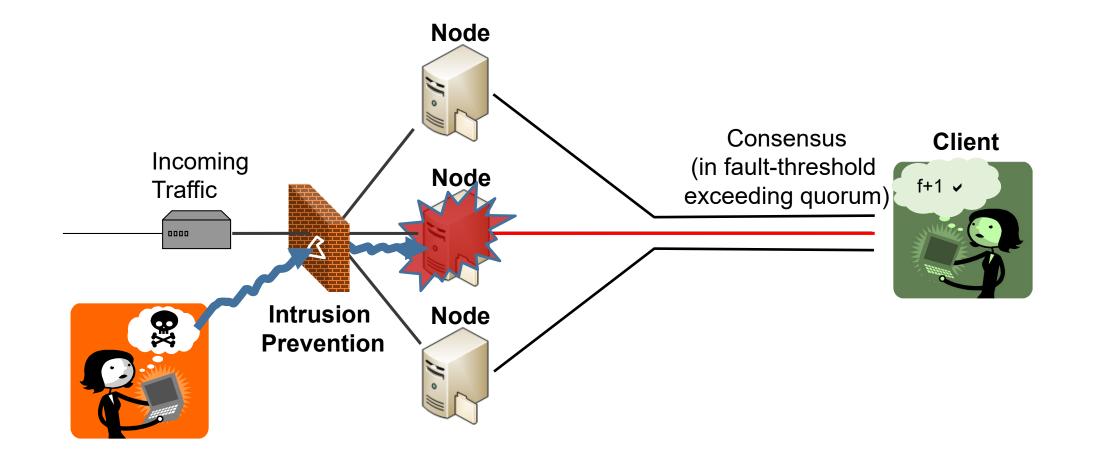






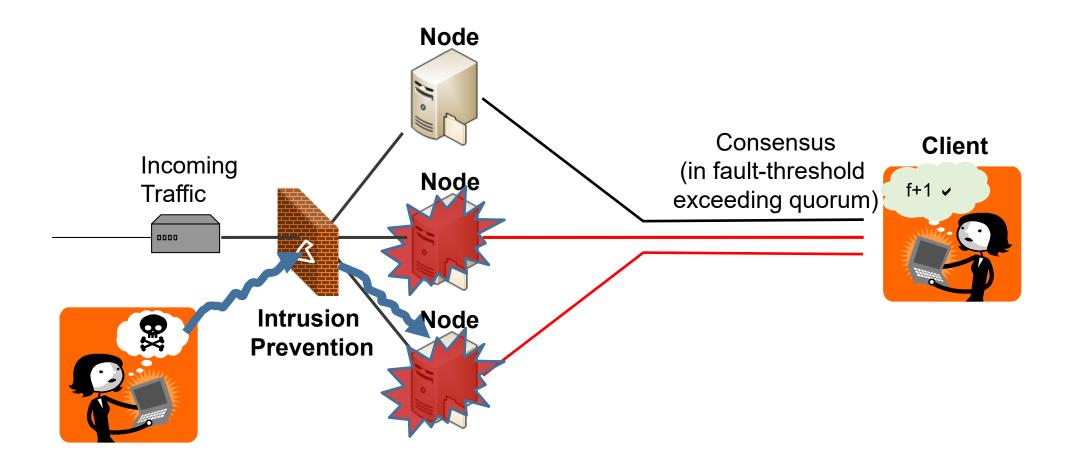






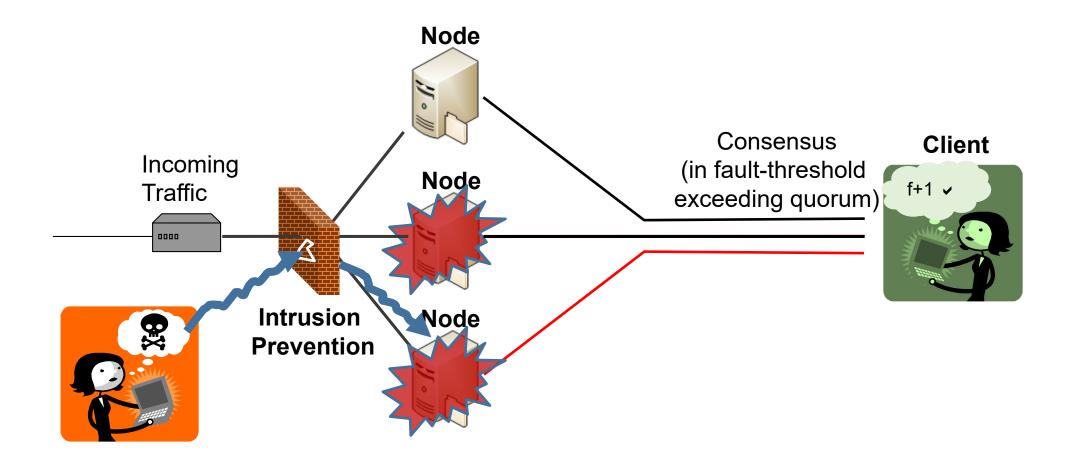


P. Sousa et al. – Exhaustion Failure



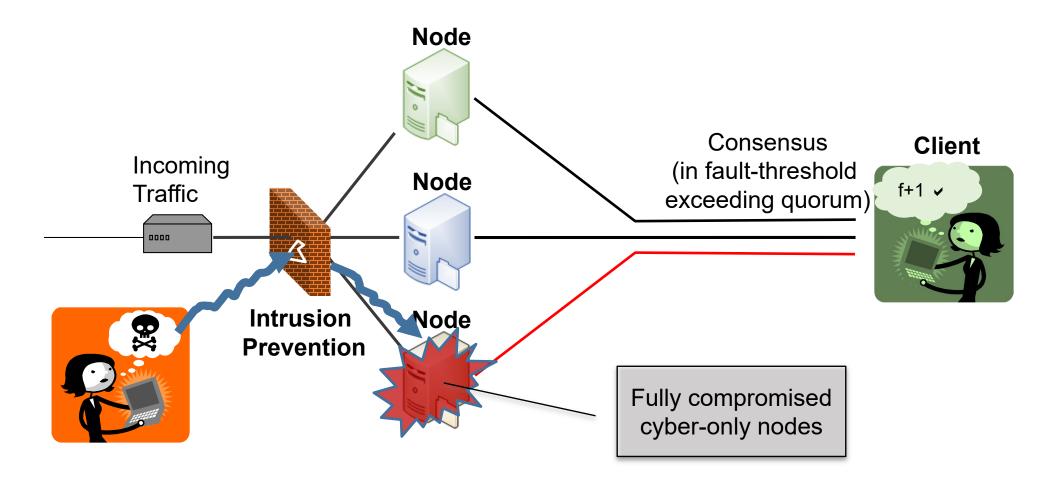


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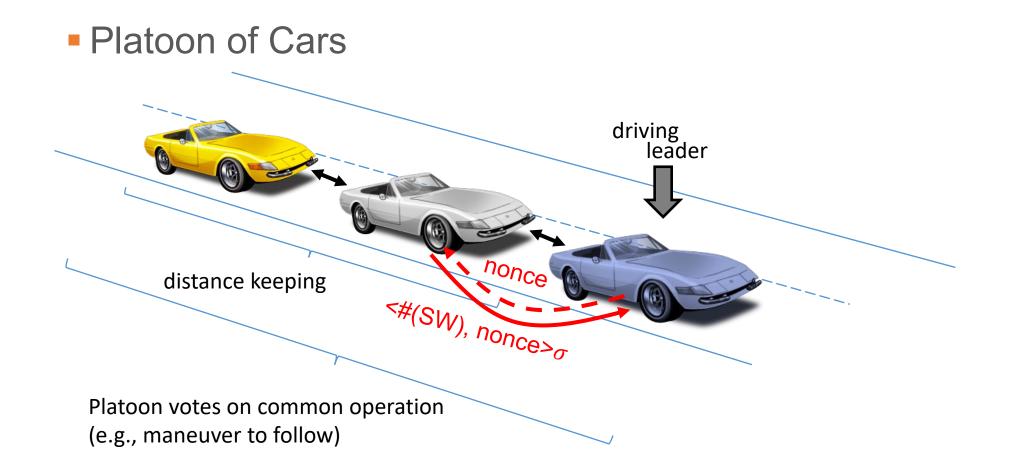


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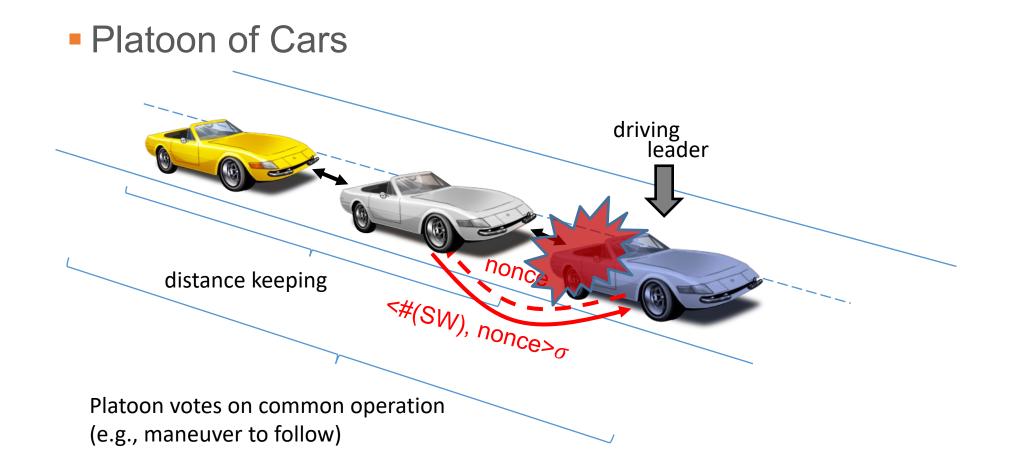
Full compromise of swarm individuals is intolerable





Full compromise of swarm individuals is intolerable



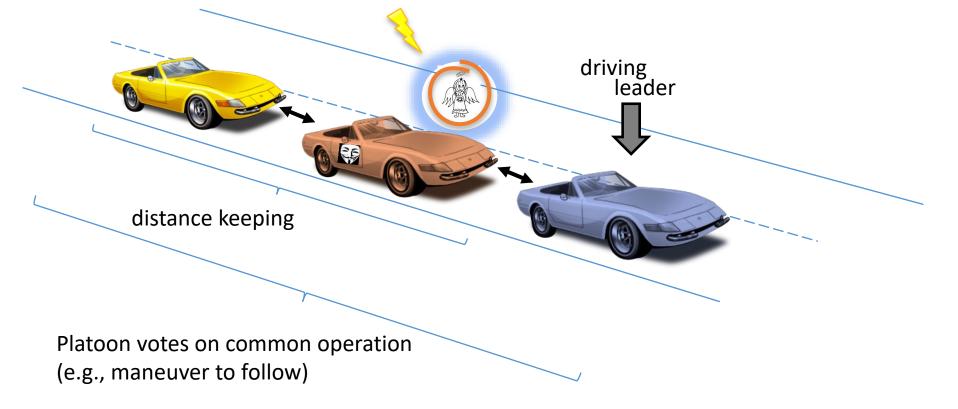


Full compromise of swarm individuals is intolerable





Safeguard safety through trusted trustworthy components

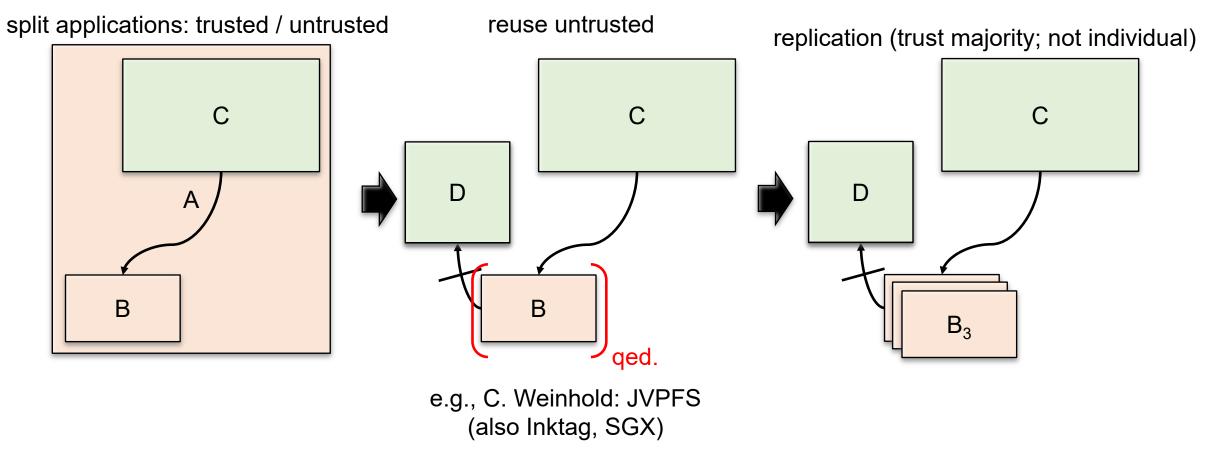


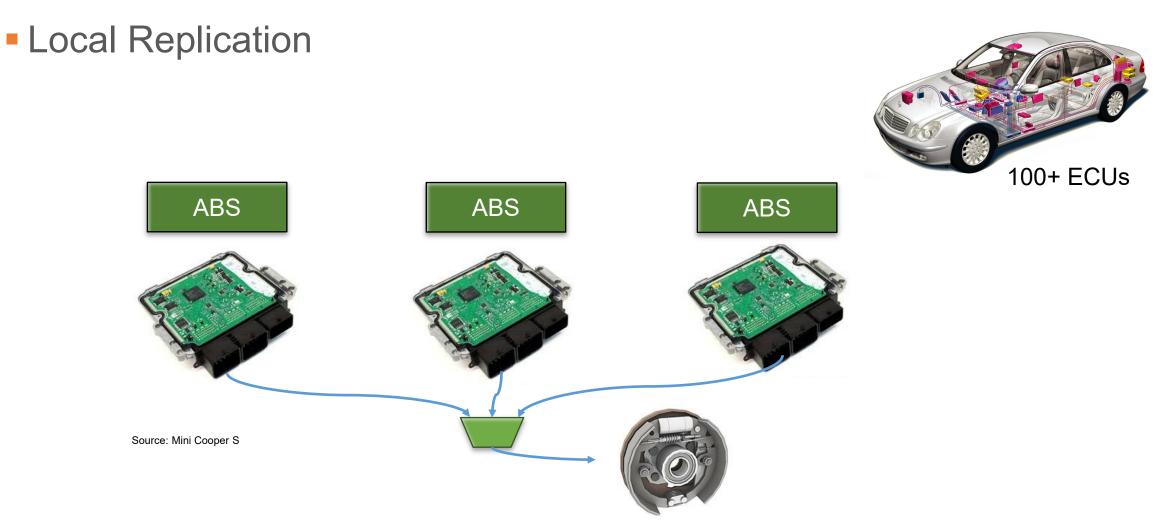
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Known Strategies for TCB Reduction





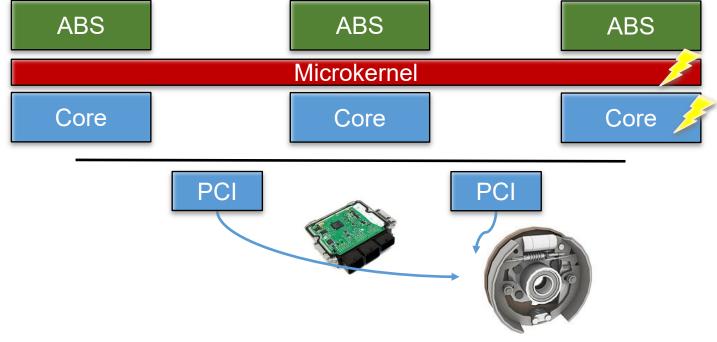
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Local Replication

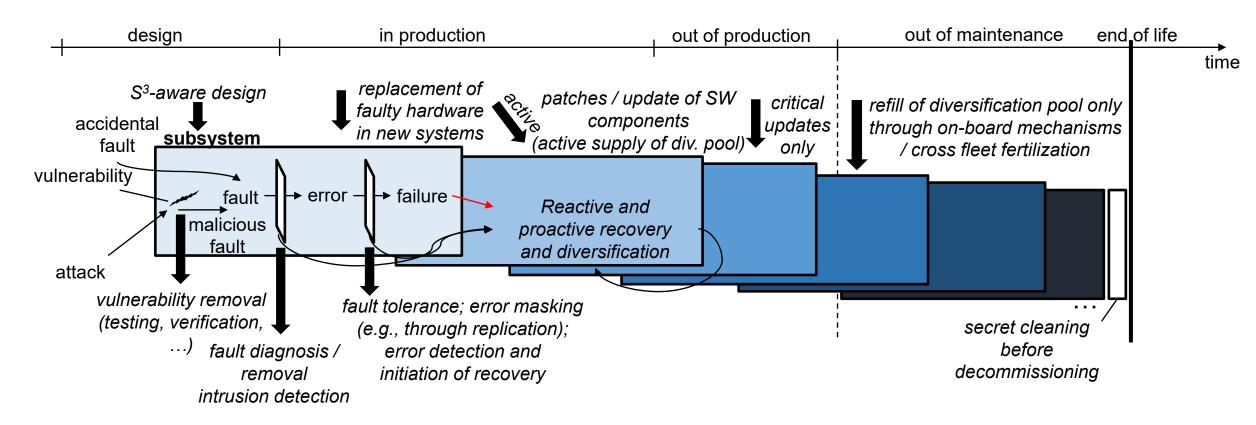




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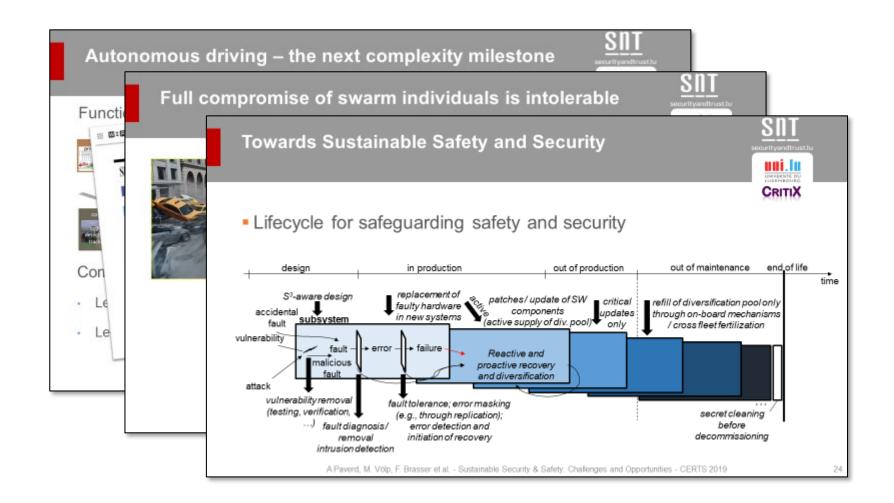


Lifecycle for safeguarding safety and security



This Talk in one Slide





We are hiring bright PhD students and postdocs!